

Practical Temperature Measurements



Agenda

- ✿ **Background, history**
- ✿ **Mechanical sensors**
- ✿ **Electrical sensors**
 - ✿ Optical Pyrometer
 - ✿ RTD
 - ✿ Thermistor, IC
 - ✿ Thermocouple
- ✿ **Summary & Examples**

What is Temperature?

- ✿ A scalar quantity that determines the direction of heat flow between two bodies
- ✿ A statistical measurement
- ✿ A difficult measurement
- ✿ A mostly empirical measurement

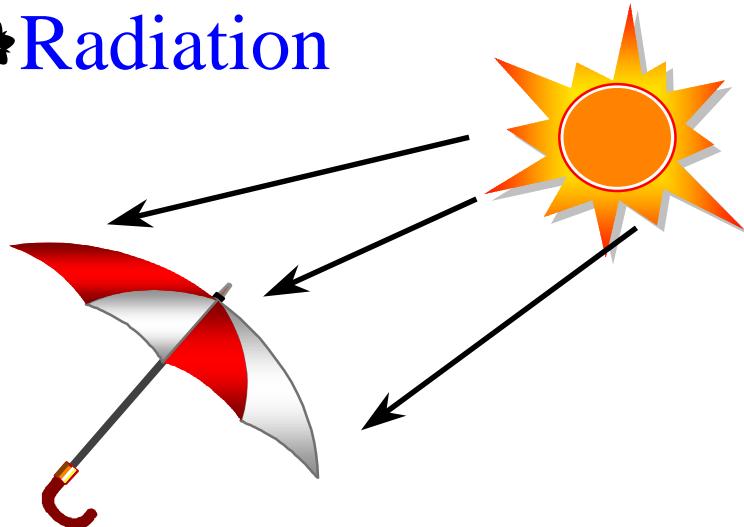
How is heat transferred?

✿ Conduction

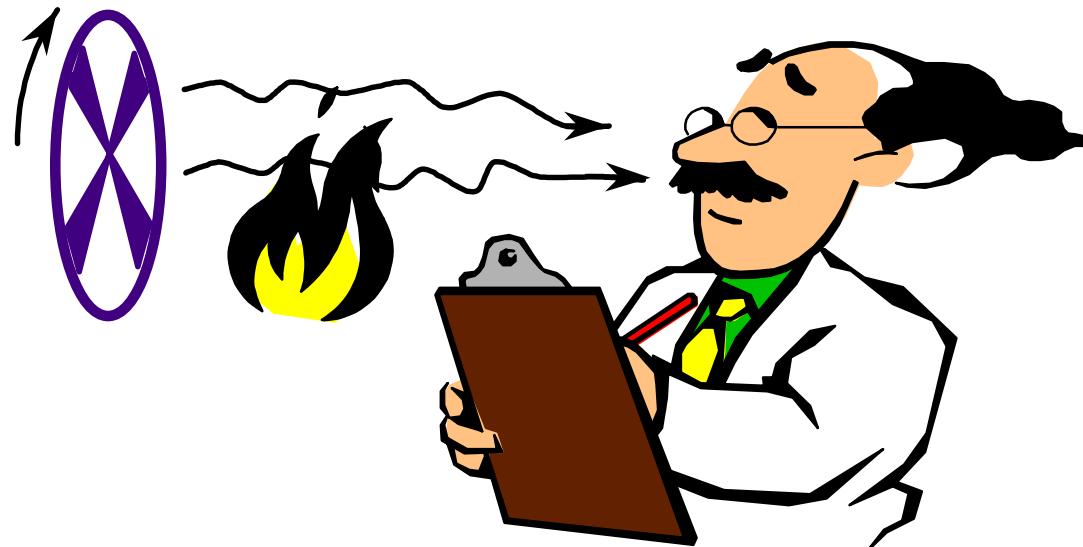
- ✿ Metal coffee cup



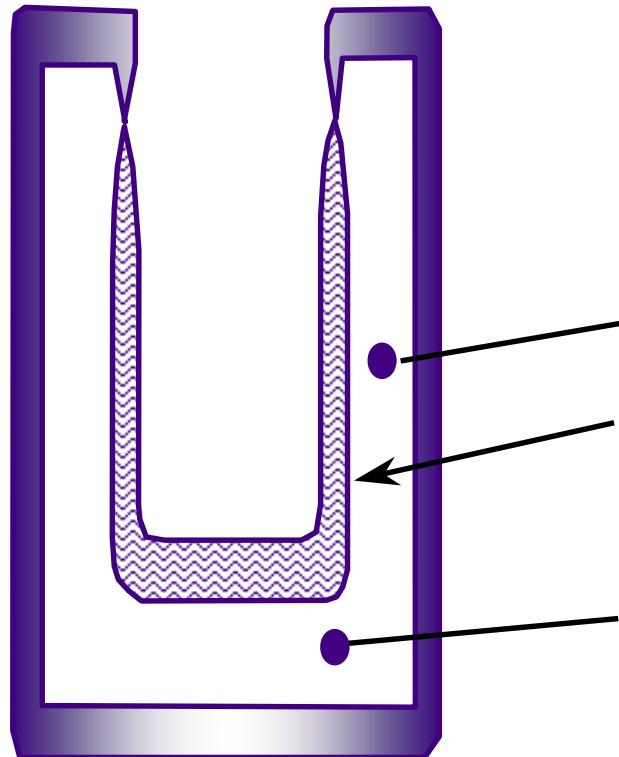
✿ Radiation



✿ Convection

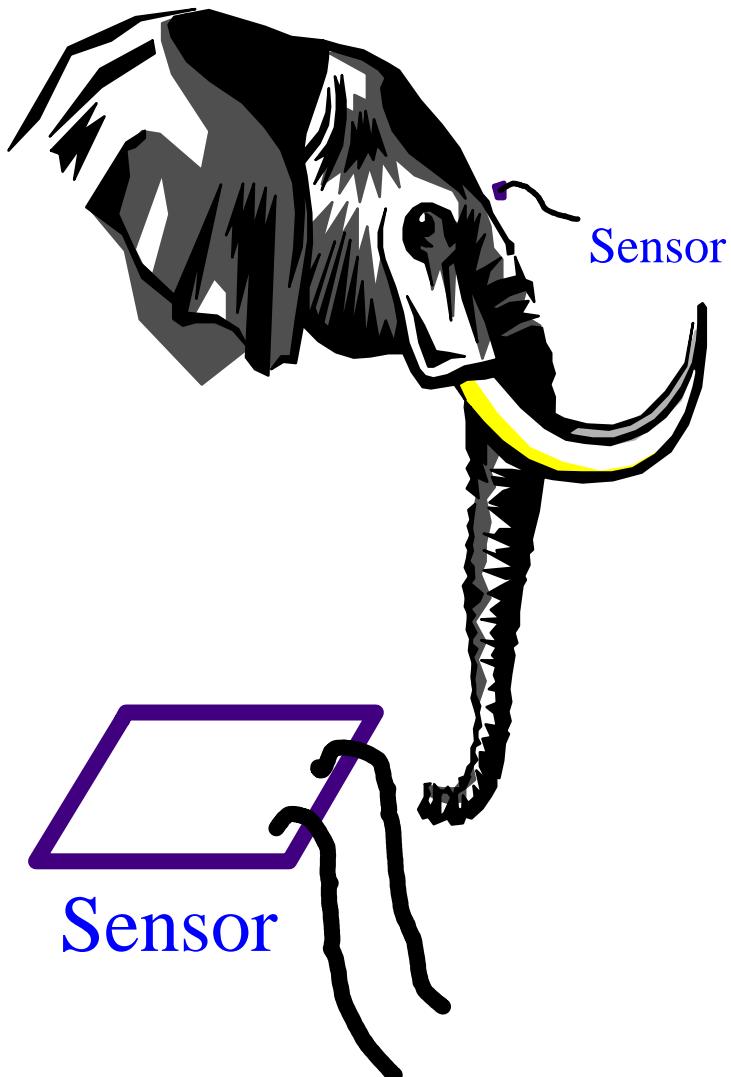


The Dewar



- ✿ Glass is a poor conductor
- ✿ Gap reduces conduction
- ✿ Metallization reflects radiation
- ✿ Vacuum reduces convection

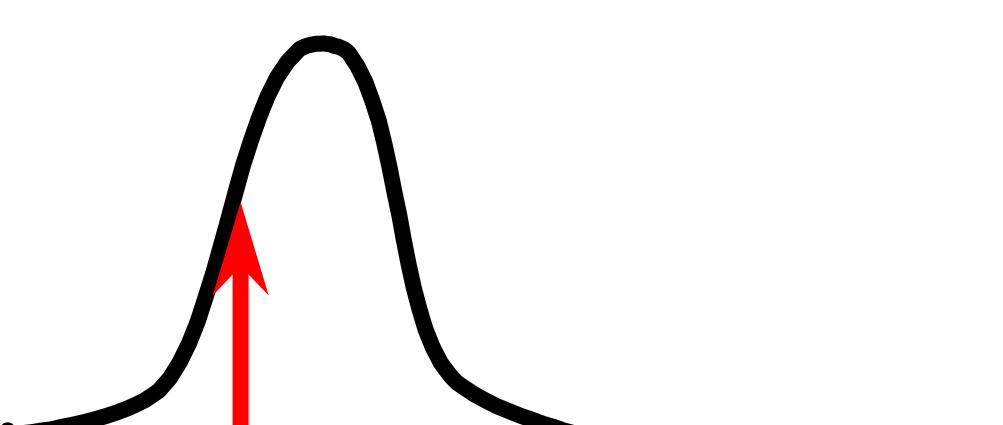
Thermal Mass



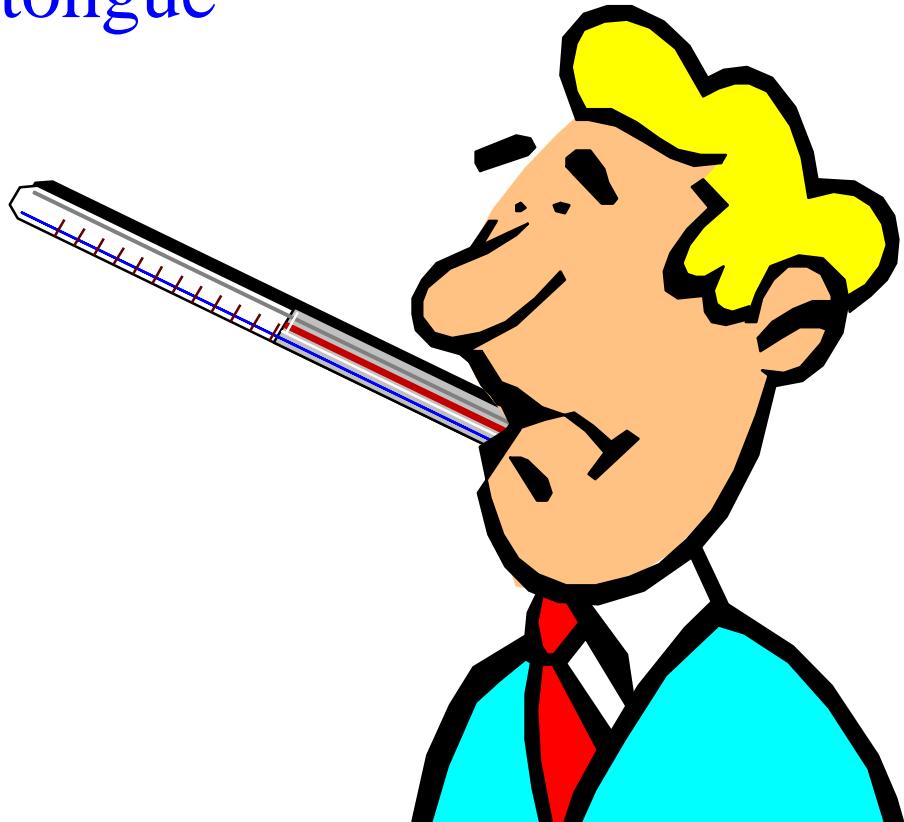
- ✿ Don't let the measuring device change the temperature of what you're measuring.
- ✿ Response time =
 - ✿ $f\{\text{Thermal mass}\}$
 - ✿ $f\{\text{Measuring device}\}$

Temperature errors

- ✿ What is YOUR normal temperature?
- ✿ Thermometer accuracy, resolution
- ✿ Contact time
- ✿ Thermal mass of thermometer, tongue
- ✿ Human error in reading



97.6 98.6 99.6
36.5 37 37.5



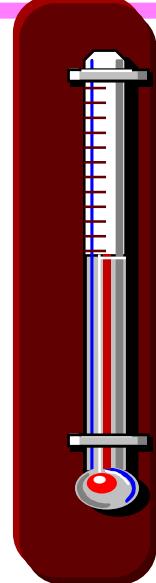
History of temperature sensors

✿ 1600 ad



✿ Galileo: First temp. sensor

- ✿ pressure-sensitive
- ✿ not repeatable

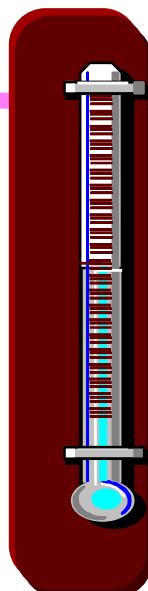


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✿ Early thermometers

- ✿ Not repeatable
- ✿ No good way to calibrate

✿ 1700 ad



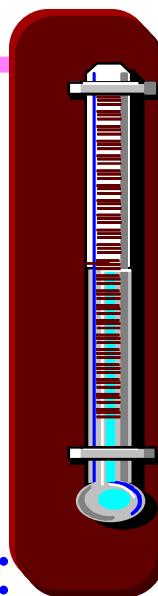
96
0

✿ Fahrenheit

- ✿ Instrument Maker
- ✿ $12*8=96$
- ✿ points
- ✿ Hg:
- ✿ Repeatable
- ✿ One standard scale

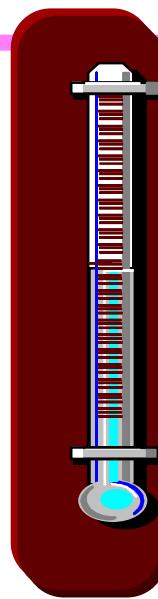
The 1700's: Standardization

✿ 1700 ad



0
100
100
0

✿ 1800 ad



✿ Thomson effect
✿ Absolute zero

✿ Celsius:

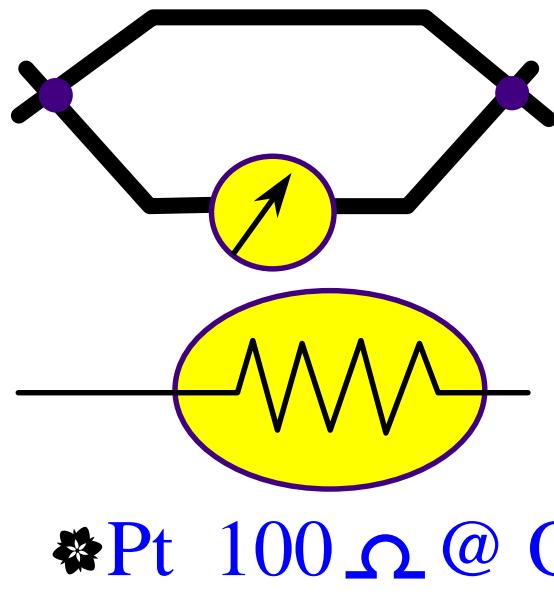
✿ Common,
repeatable
calibration reference
points

✿ "Centigrade"
scale

1821: It was a very good year

✿ 1800 ad

✿ 1900 ad



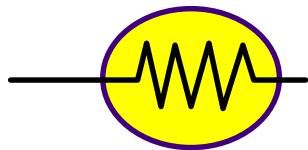
✿ The Seebeck effect

✿ Davy: The RTD

✿ Pt 100 Ω @ 0 deg.C

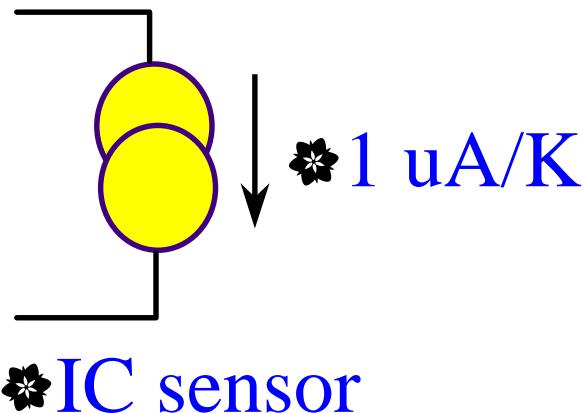
The 1900's: Electronic sensors

✿ 1900 ad



✿ Thermistor

✿ 2000 ad



✿ IC sensor

✿ IPTS 1968

✿ IPTS 1990

- ✿ "Degree Kelvin">>> "kelvins"
- ✿ "Centigrade">>> " Celsius"

Temperature scales

Absolute
zero

Freezing
point H_2O

Boiling point
 H_2O_2

-273.15  Celsius

0

100

0  Kelvin

273.15

373.15

-459.67  Fahrenheit

32

212

0  Rankine

427.67

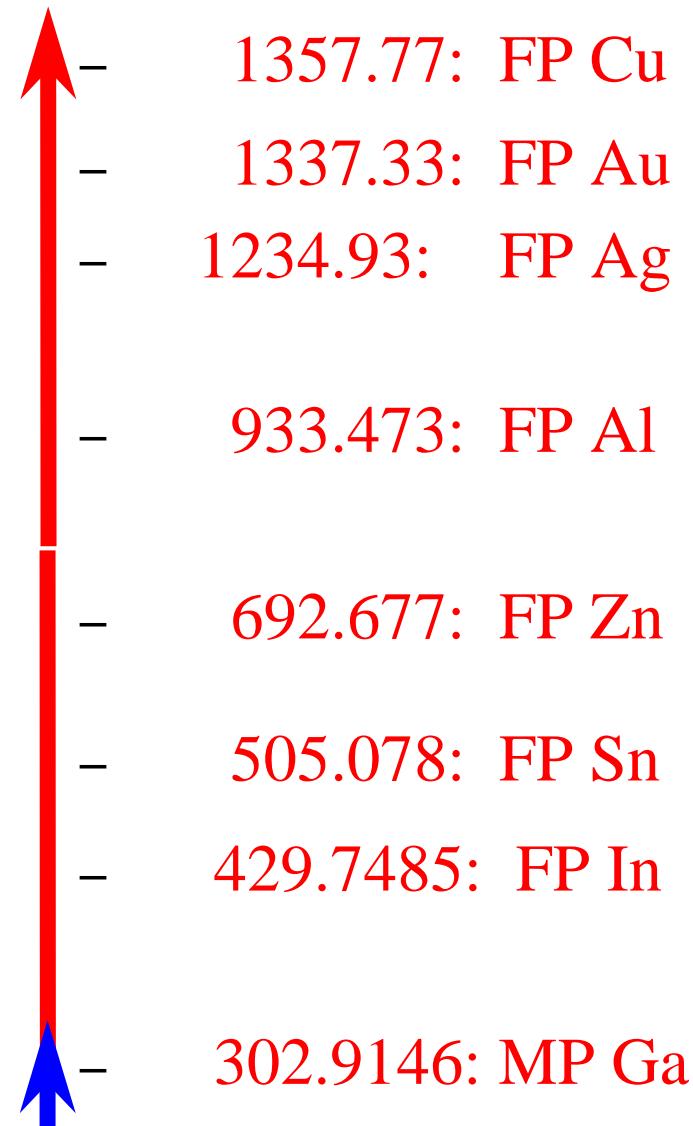
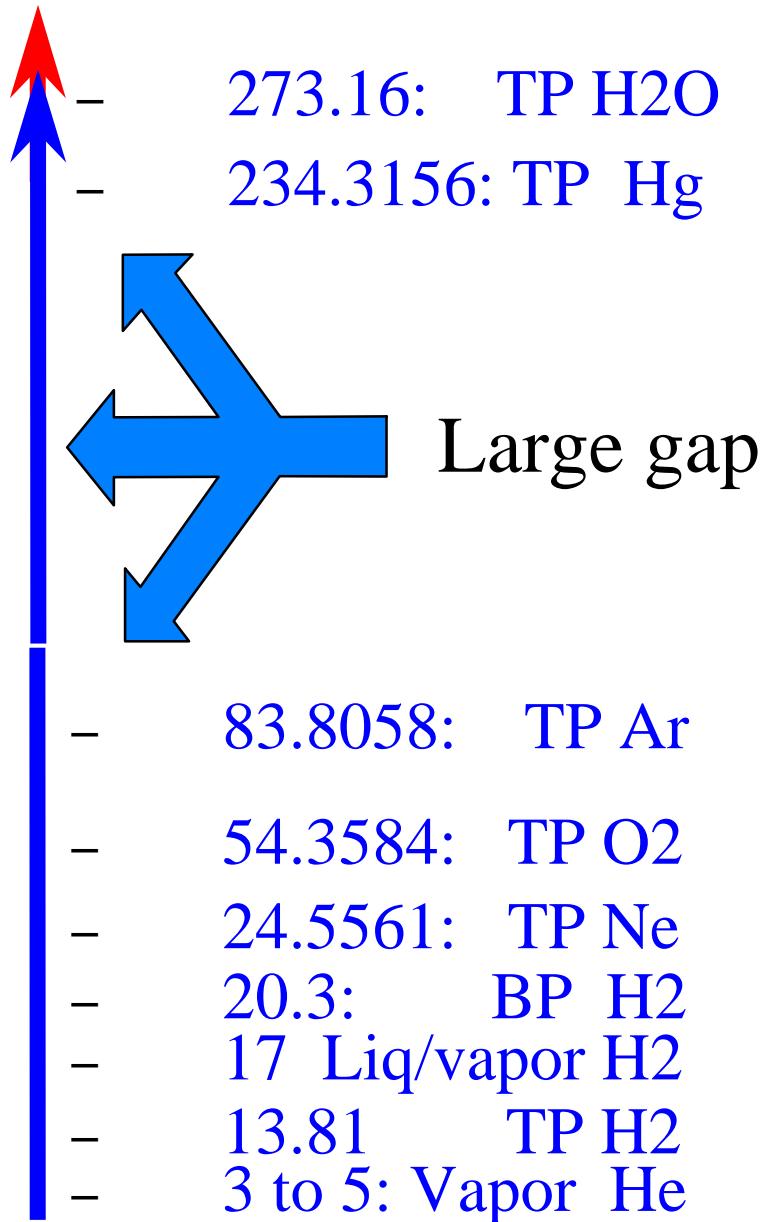
671.67

 "Standard" is "better":

-  Reliable reference points
-  Easy to understand



IPTS '90: More calibration points



Agenda

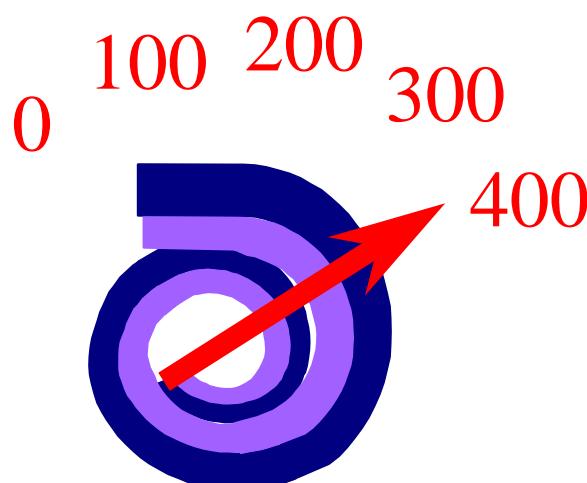
- ✿ Background, history
- ✿ **Mechanical sensors**
- ✿ Electrical sensors
 - ✿ Optical Pyrometer
 - ✿ RTD
 - ✿ Thermistor, IC
 - ✿ Thermocouple
- ✿ Summary & Examples

Bimetal thermometer

❖ Two dissimilar metals, tightly bonded

❖ Forces due to thermal expansion

❖ Result

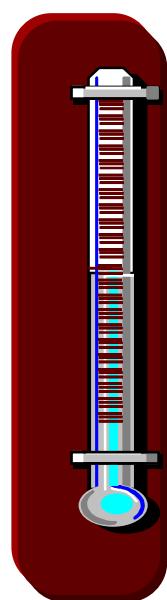


❖ Bimetallic thermometer

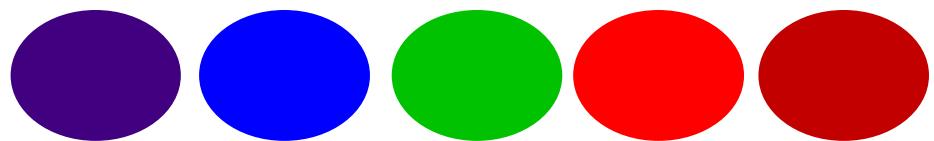
- ❖ Poor accuracy
- ❖ Hysteresis

❖ Thermal expansion causes big problems in other designs:

- ❖ IC bonds
- ❖ Mechanical interference



Liquid thermometer; Paints



- ✿ Thermally-sensitive paints
 - ✿ Irreversible change
 - ✿ Low resolution
 - ✿ Useful in hard-to-measure areas

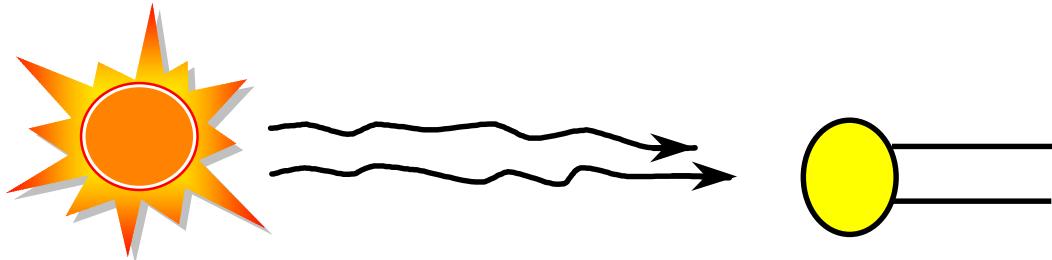
✿ Liquid-filled thermometer

- ✿ Accurate over a small range
- ✿ Accuracy & resolution = $f(\text{length})$
- ✿ Range limited by liquid
- ✿ Fragile
- ✿ Large thermal mass
- ✿ Slow

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Optical Pyrometer

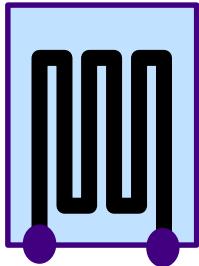


- ✿ Infrared Radiation-sensitive
- ✿ Photodiode or photoresistor
- ✿ Accuracy = $f\{\text{emissivity}\}$
- ✿ Useful @ very high temperatures
- ✿ Non-contacting
- ✿ Very expensive
- ✿ Not very accurate

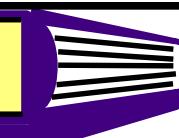
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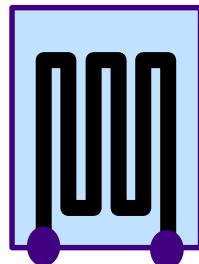
Resistance Temperature Detector



- ✿ Most accurate & stable
- ✿ Good to 800 degrees Celsius
- ✿ $\text{Resistance} = f\{\text{Absolute T}\}$
- ✿ Self-heating a problem
- ✿ Low resistance
- ✿ Nonlinear



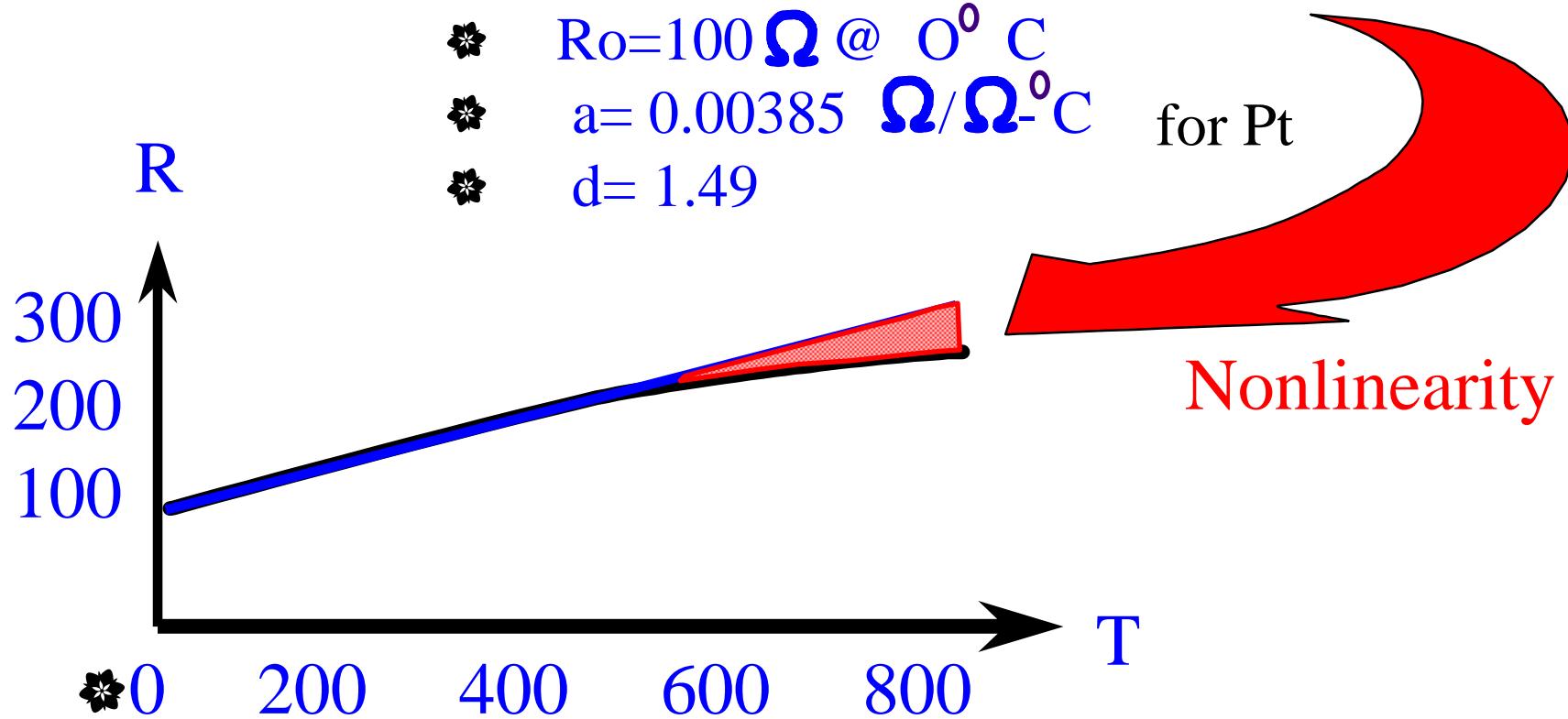
RTD Equation



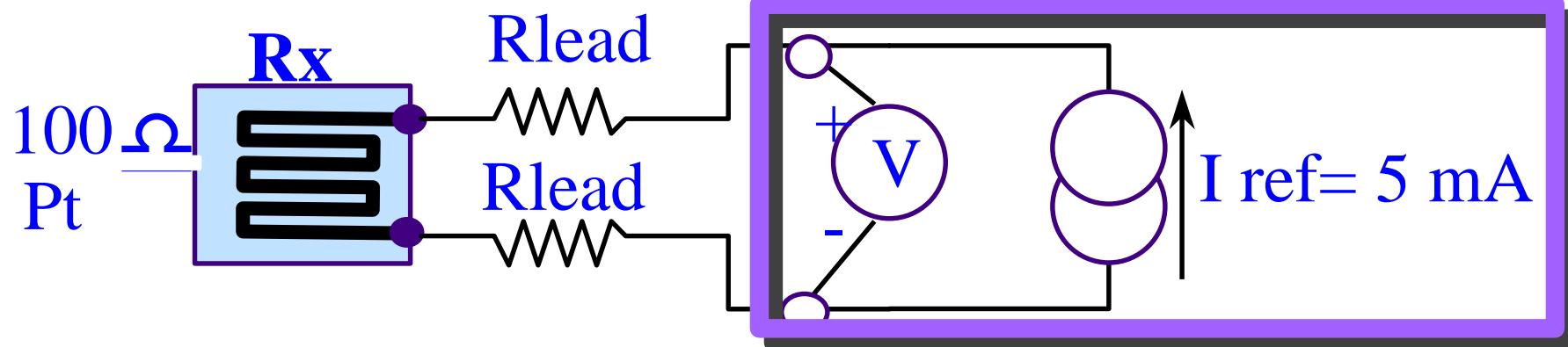
- ✿ $R = 100 \text{ Ohms} @ 0^\circ \text{C}$
- ✿ Callendar-Van Deusen Equation:

For $T > 0^\circ \text{C}$: ✿ $R = R_0(1 + aT) - R_0(ad(.01T)(.01T-1))$

- ✿ $R_0 = 100 \Omega @ 0^\circ \text{C}$
- ✿ $a = 0.00385 \Omega/\Omega^\circ \text{C}$ for Pt
- ✿ $d = 1.49$

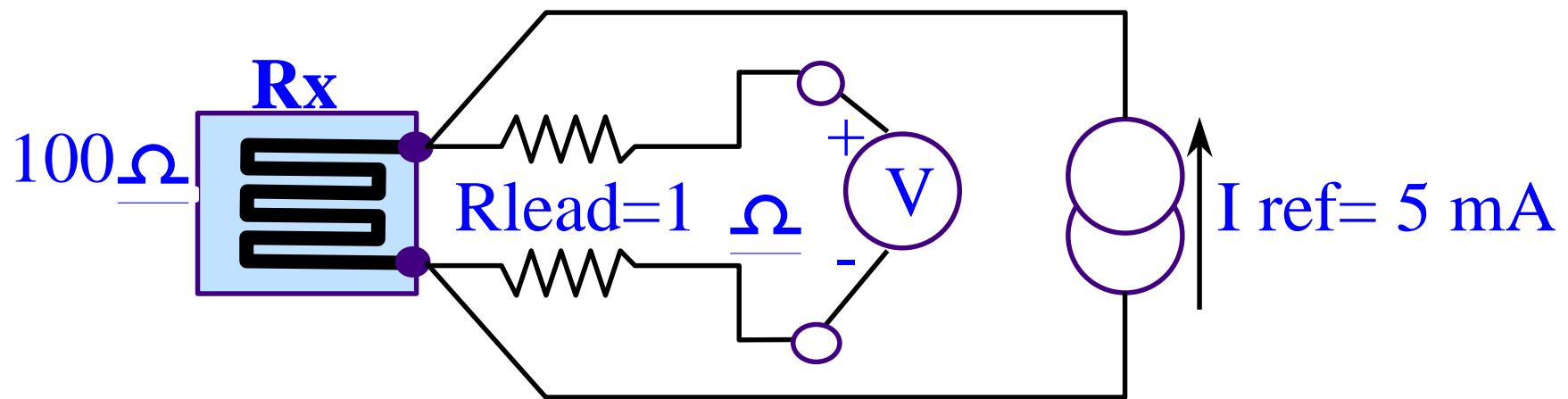


Measuring an RTD: 2-wire method



- ✿ $R = I_{ref} * (Rx + 2 * R_{lead})$
- ✿ Error = $2 \frac{\Omega}{.385} =$ more than 5 degrees C for 1 ohm R_{lead} !
- ✿ Self-heating:
 - ✿ For 0.5 V signal, $I = 5\text{mA}$; $P = .5 * .005 = 2.5 \text{ mwatts}$
 - ✿ @ 1 mW/deg C, Error = 2.5 deg C!
- ✿ Moral: Minimize I_{ref} ; Use 4-wire method
- ✿ If you must use 2-wire, NULL out the lead resistance

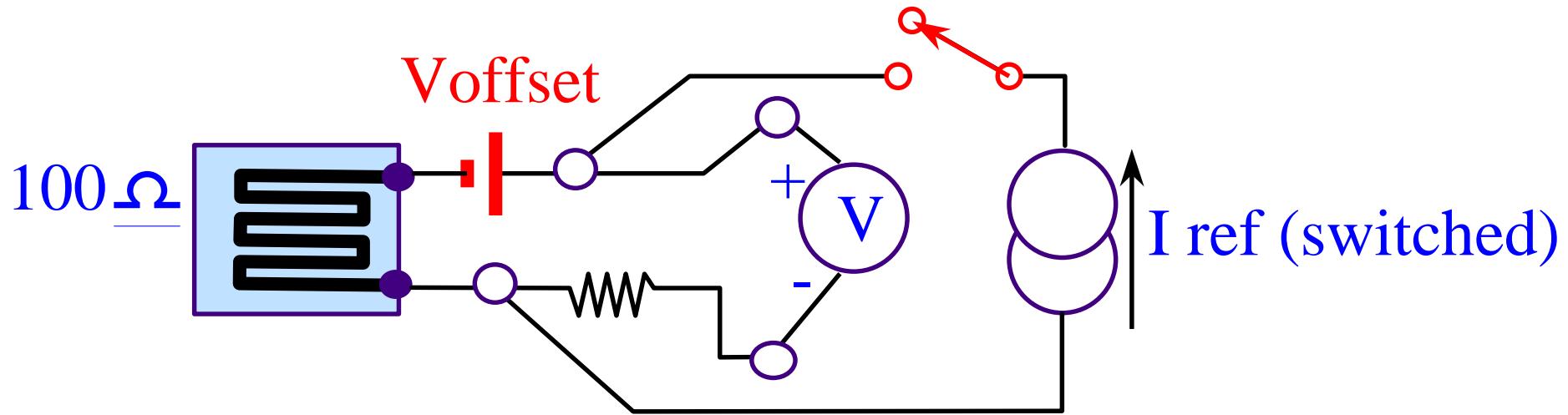
The 4-Wire technique



- ✿ $R = I_{ref} * R_x$
- ✿ Error not a function of R in source or sense leads
- ✿ No error due to *changes* in lead R

- ✿ Twice as much wire
- ✿ Twice as many scanner channels
- ✿ Usually slower than 2-wire

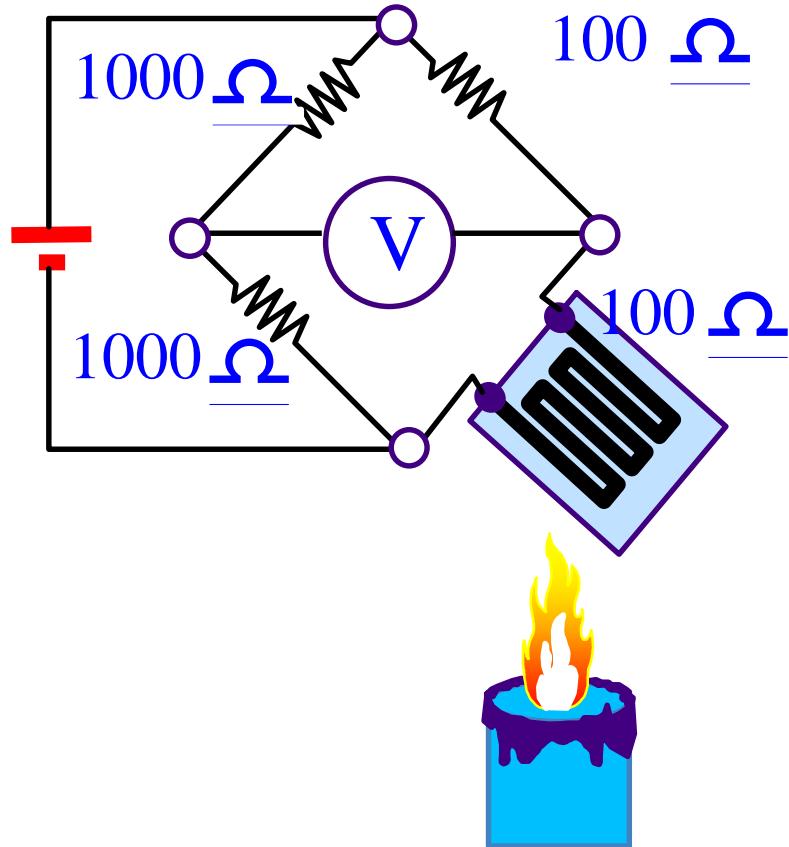
Offset compensation



- ✿ Eliminates thermal voltages
 - ✿ Measure V without I applied
 - ✿ Measure V *With* I applied

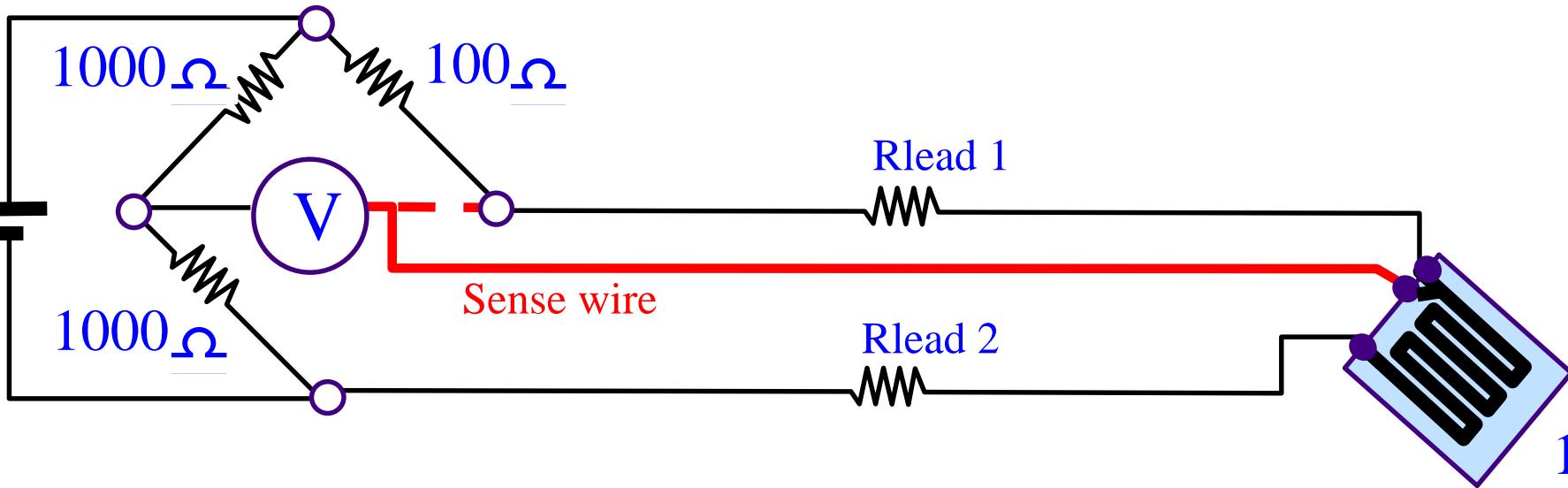
$$R = \frac{\Delta V}{\Delta I}$$

Bridge method



- ✿ High resolution (DMM stays on most sensitive range)
- ✿ Nonlinear output
- ✿ Bridge resistors too close to heat source

3-Wire bridge



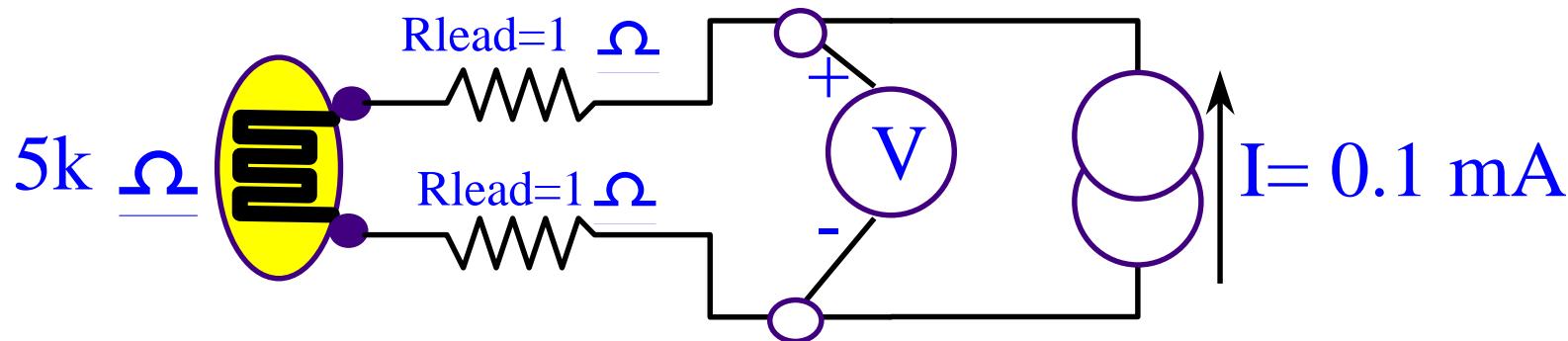
- ✿ Keeps bridge away from heat source
- ✿ Break DMM lead (dashed line); connect to RTD through 3rd "sense" wire
- ✿ If Rlead 1 = Rlead 2, sense wire makes error small
- ✿ Series resistance of sense wire causes no error



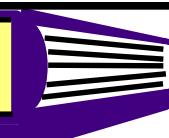
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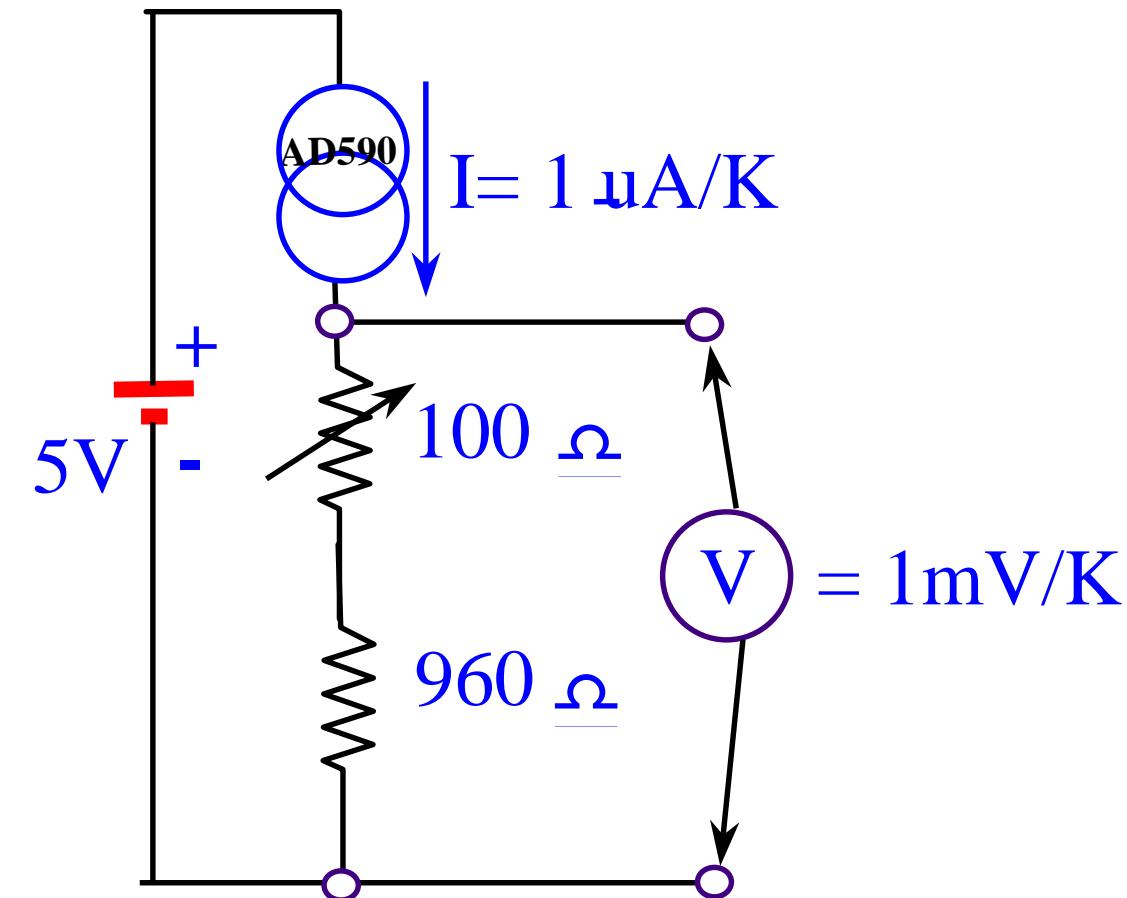
Electrical sensors: Thermistor



- ✿ Hi-Z; Sensitive: $5 k\Omega$ @ 25C; $\Delta R = 4\%/\text{deg C}$
- ✿ Limited range
- ✿ 2-Wire method: $R = I * (R_{thmr} + 2 * R_{lead})$
 - ✿ Lead R Error = $2 \Omega / 400 = 0.005$ degrees C
- ✿ Low thermal mass: High self-heating
- ✿ Very nonlinear

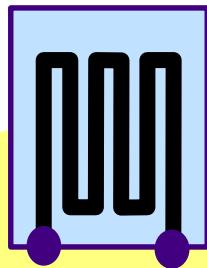


I.C. Sensor



- ✿ High output
- ✿ Very linear
- ✿ Accurate @ room ambient
- ✿ Limited range
- ✿ Cheap

Summary: Absolute T devices



RTD

- ✿ Most accurate
- ✿ Most stable
- ✿ Fairly linear
- ✿ Expensive
- ✿ Slow
- ✿ Needs I source
- ✿ Self-heating
- ✿ 4-wire meas.



Thermistor

- ✿ High output
- ✿ Fast
- ✿ 2-wire meas.
- ✿ Very nonlinear
- ✿ Limited range
- ✿ Needs I source
- ✿ Self-heating
- ✿ Fragile



I.C.

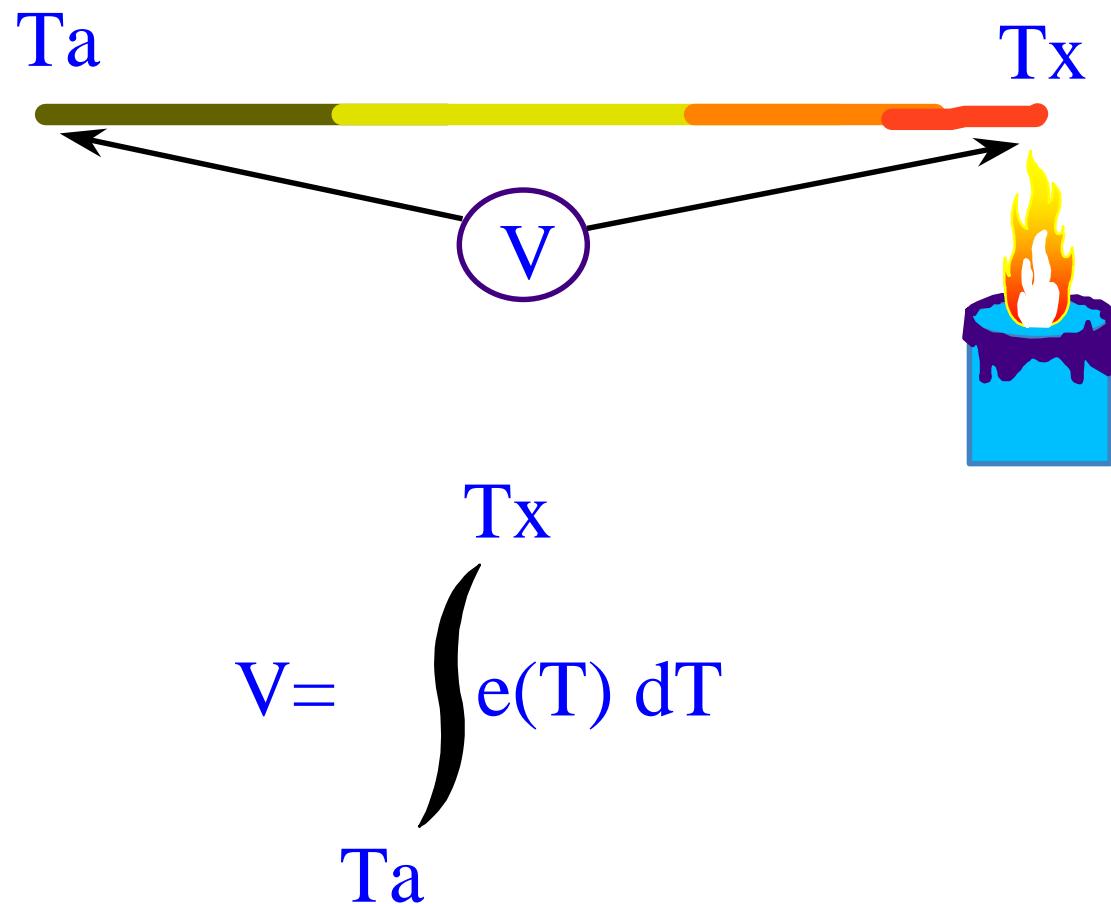
- ✿ High output
- ✿ Most linear
- ✿ Inexpensive
- ✿ Limited variety
- ✿ Limited range
- ✿ Needs V source
- ✿ Self-heating

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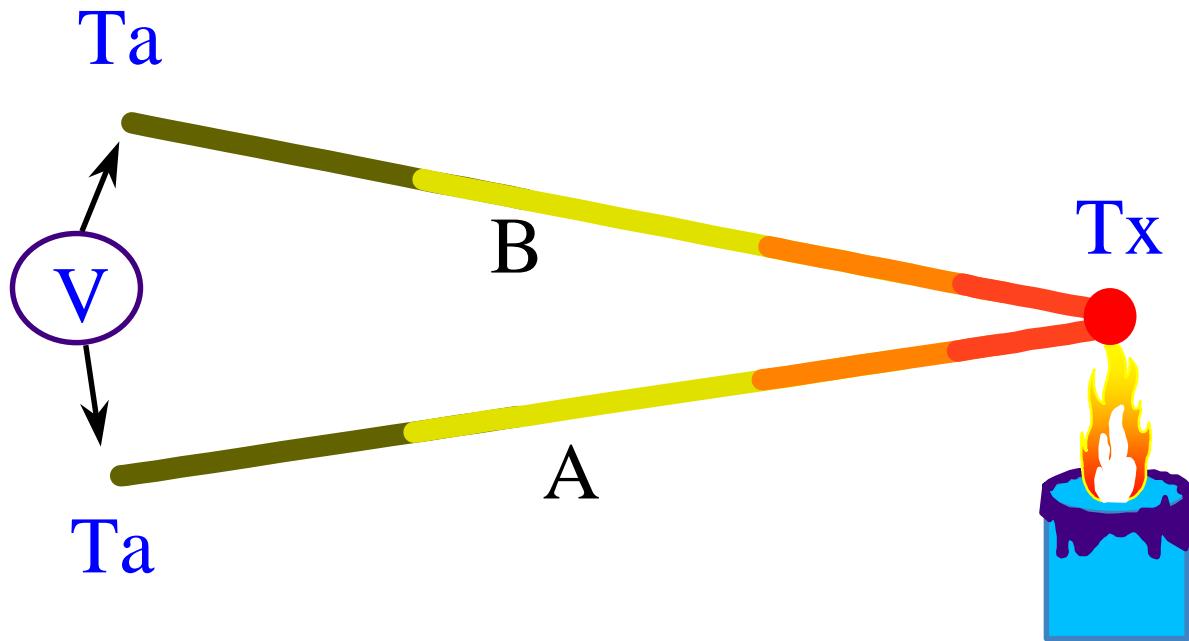
Thermocouples

The Gradient Theory



- ✿ The WIRE is the sensor, not the junction
- ✿ The Seebeck coefficient (e) is a function of temperature

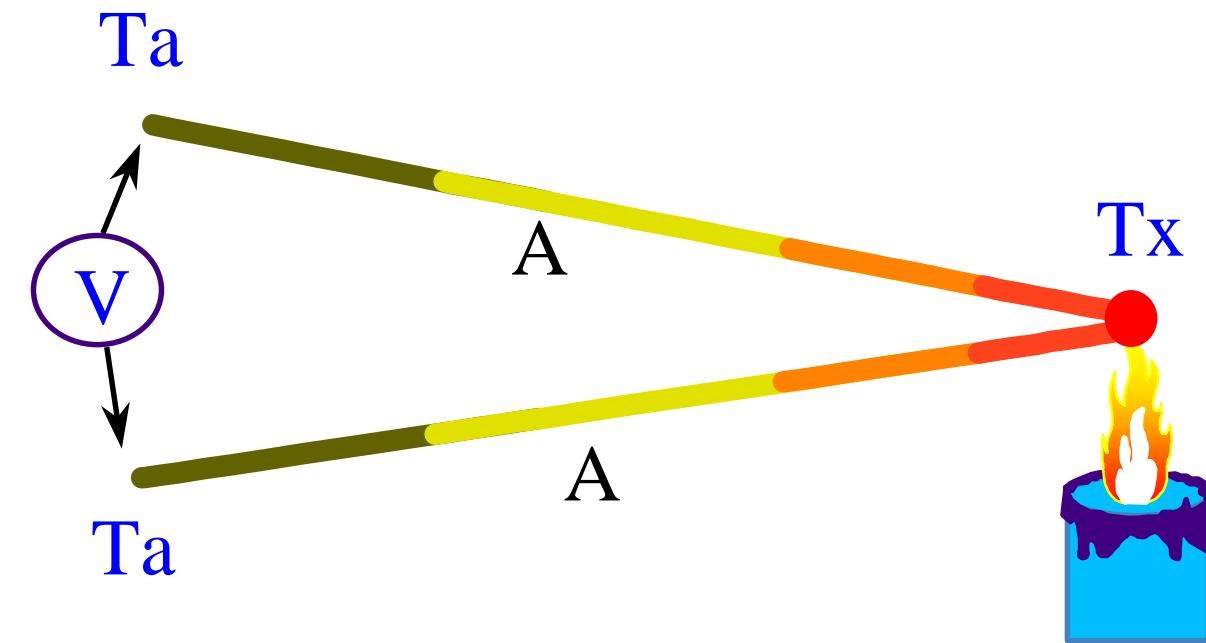
Making a thermocouple



$$V = \int_{T_a}^{T_x} e_A dT + \int_{T_x}^{T_a} e_B dT$$

- ✿ Two wires make a thermocouple
- ✿ Voltage output is nonzero if metals are not the same

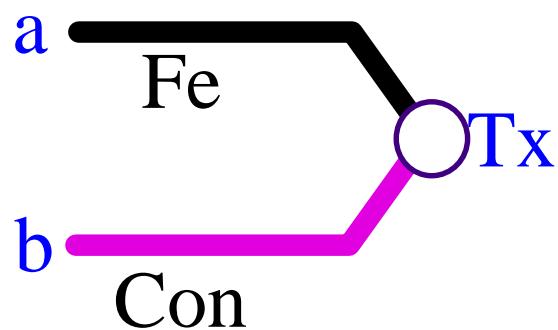
Gradient theory also says...



$$V = \int_{T_a}^{T_x} e_A dT + \int_{T_x}^{T_a} e_A dT = 0$$

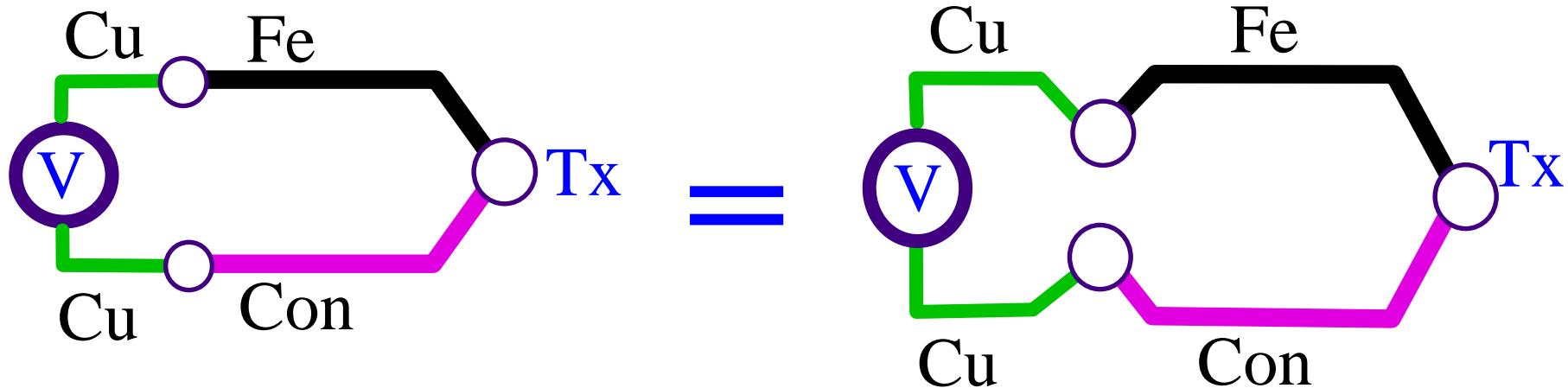
✿ If wires are the same type, or if there is one wire, and both ends are at the same temperature, output=Zero.

Now try to measure it:



✿ Theoretically,
 $V_{ab} = f\{Tx - Tab\}$

✿ But, try to measure it with a DMM:

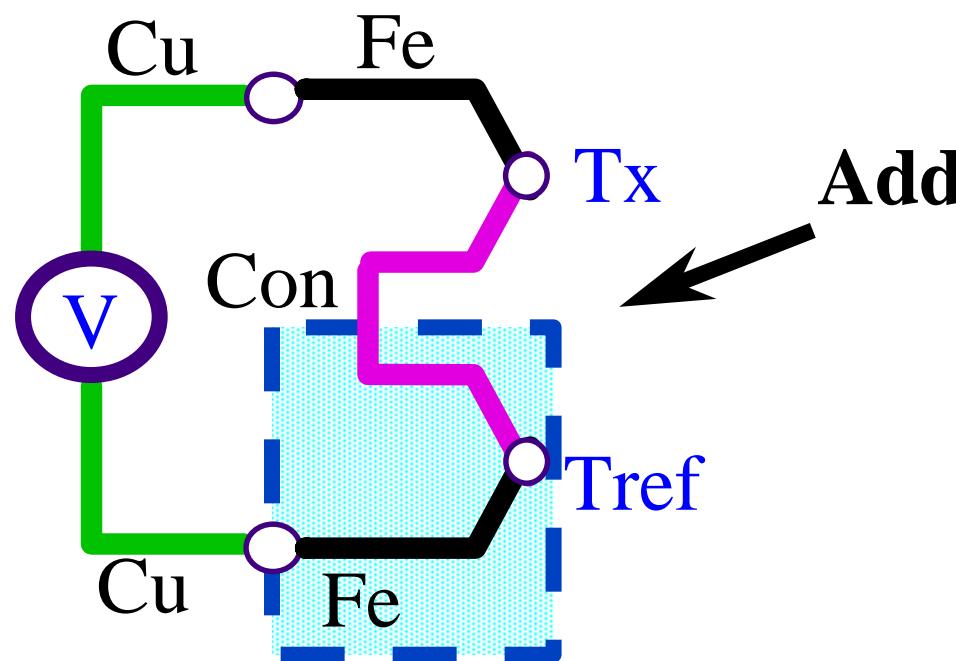


✿ Result: 3 unequal junctions, all at unknown temperatures

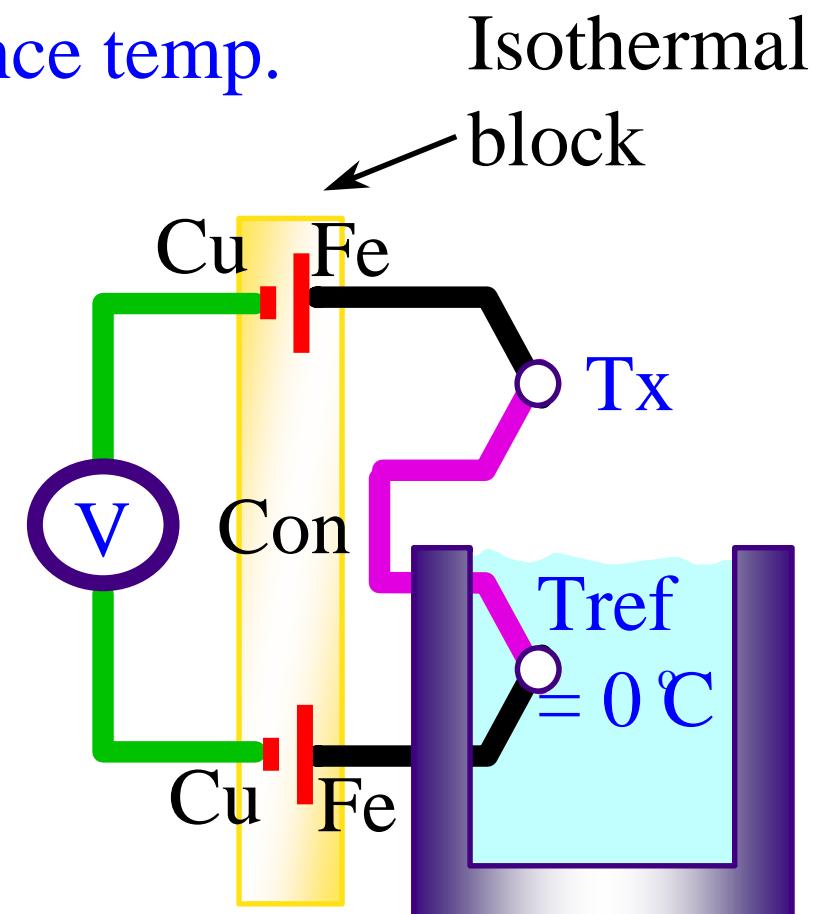
Solution: Reference Thermocouple

✿ Problems: a) 3 different thermocouples,
b) 3 unknown temperatures

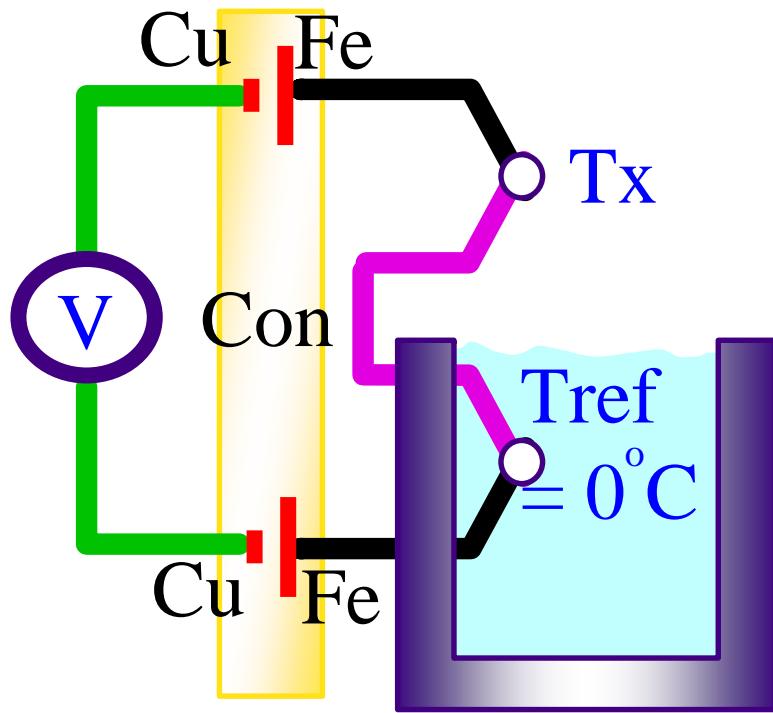
✿ Solutions: a) Add an opposing thermocouple
b) Use a known reference temp.



Add



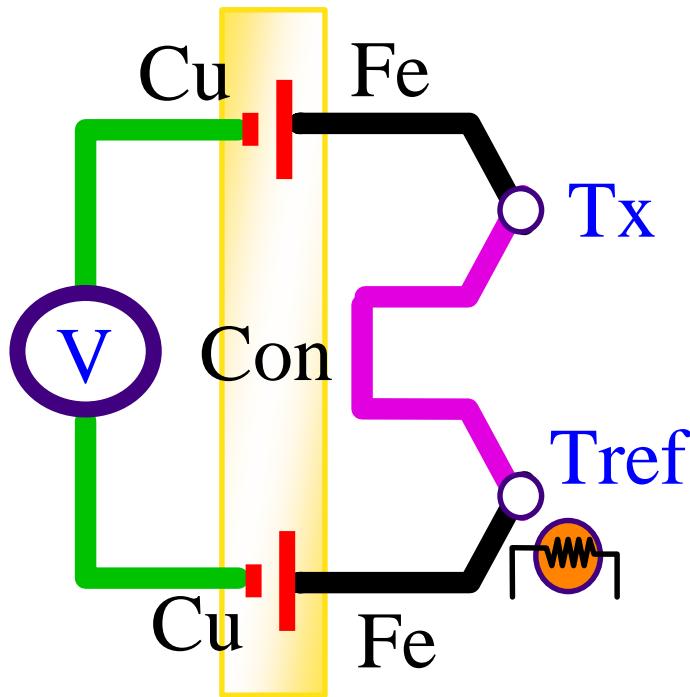
The Classical Method



- ✿ If both Cu junctions are at same T , the two "batteries" cancel
- ✿ T_{ref} is an ice bath (sometimes an electronic ice bath)
- ✿ All T/C tables are referenced to an ice bath
- ✿ $V = f\{T_x - T_{ref}\}$

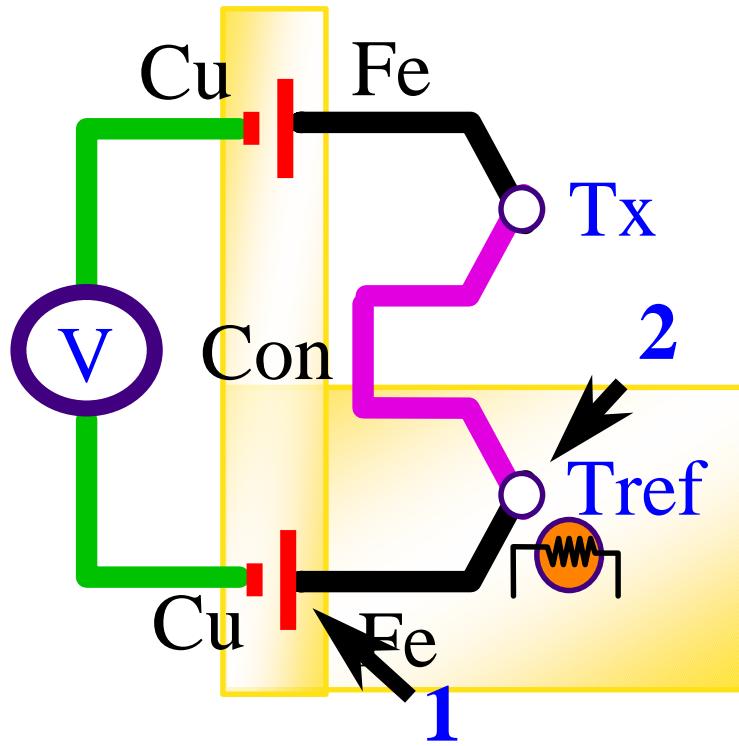
- ✿ Question: How can we eliminate the ice bath?

Eliminating the ice bath

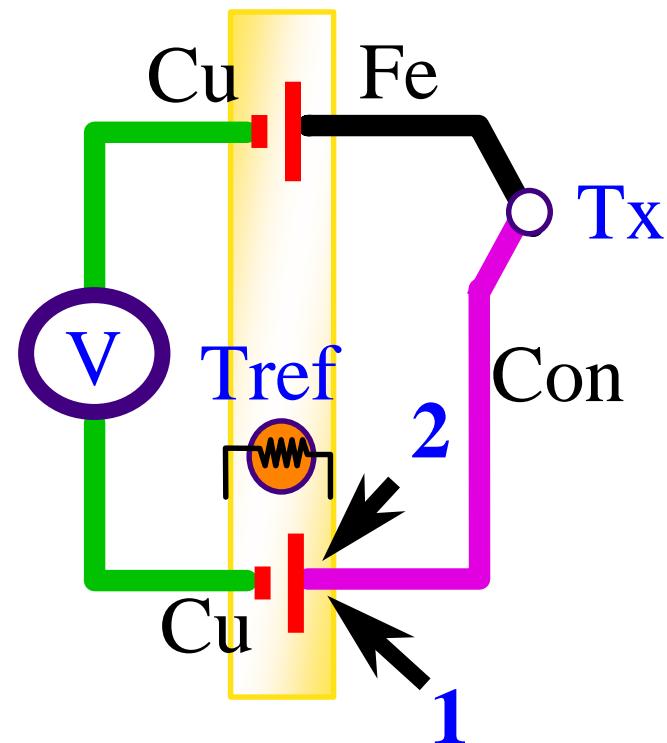


- ✿ Don't force T_{ref} to ice point, just measure it
- ✿ Compensate for T_{ref} mathematically:
$$V = f\{ T_x \mid_{T_{ice}} - T_{ref} \mid_{T_{ice}} \}$$
- ✿ If we know $T_{ref} \mid_{T_{ice}}$, we can compute T_x .

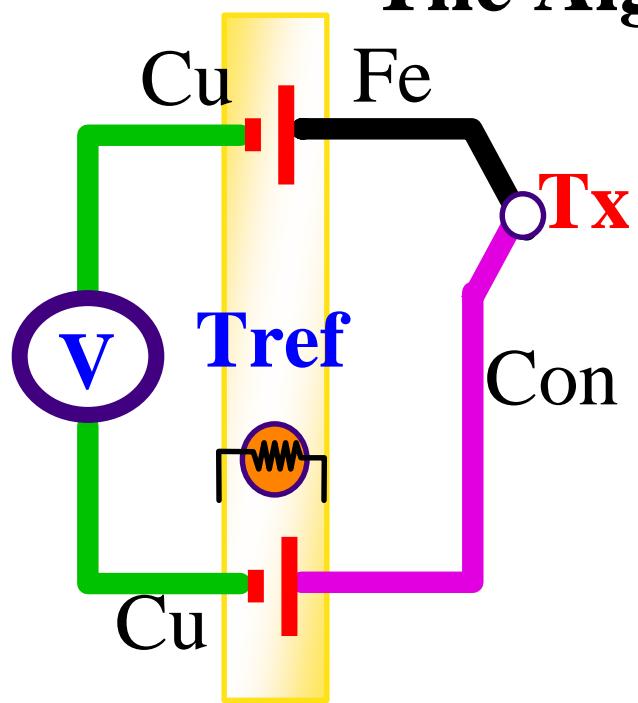
Eliminating the second T/C



- ✿ Extend the isothermal block
- ✿ If isothermal, $V_1 - V_2 = 0$

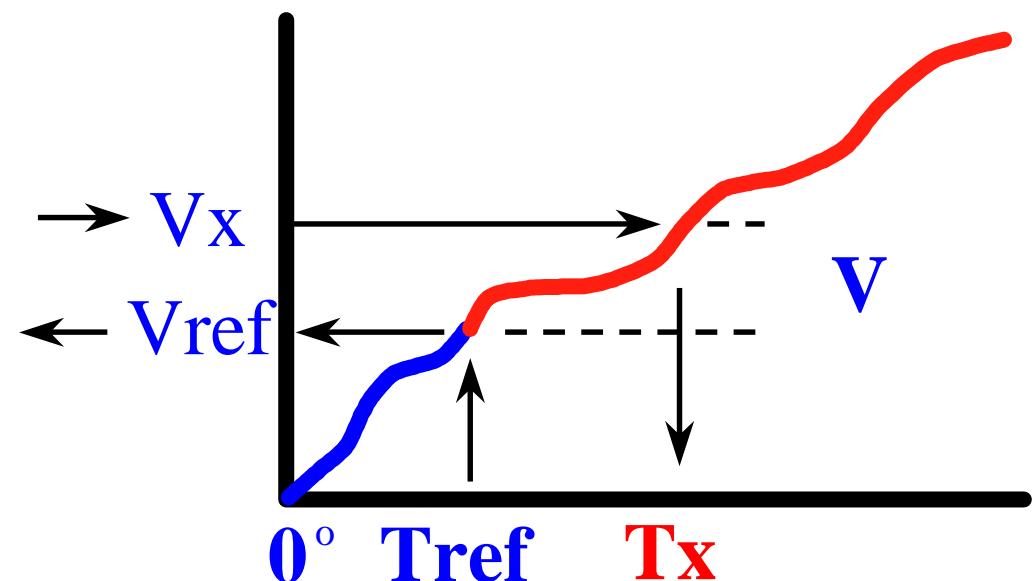


The Algorithm for one T/C

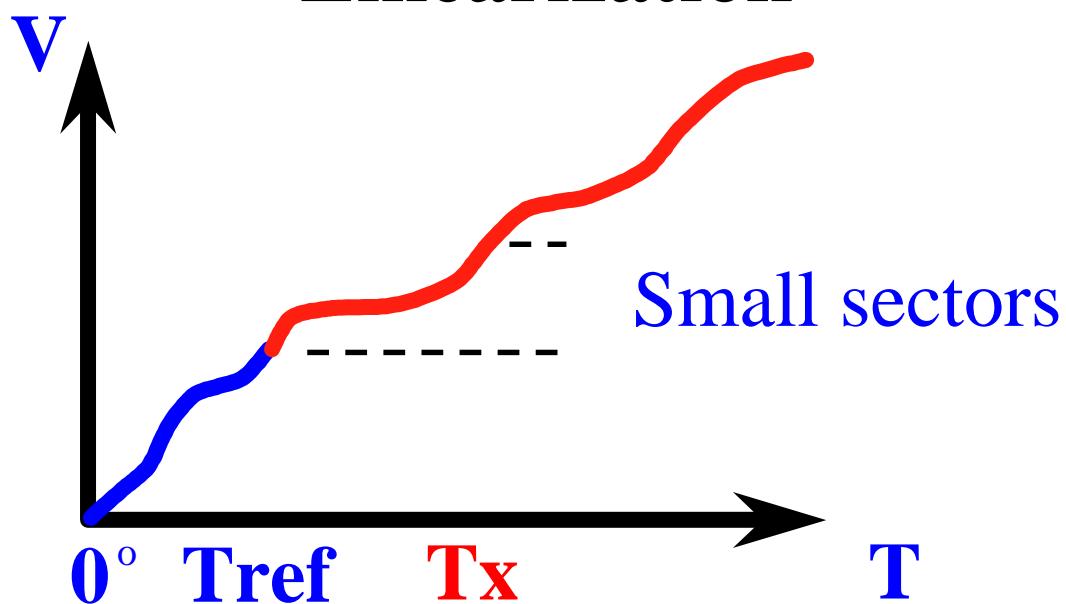


Compute
 $V_x = V + V_{ref}$

- ✿ Measure T_{ref} : RTD, IC or thermistor
- ✿ $T_{ref} \implies V_{ref} @ 0^\circ C$ for Type J(Fe-C)
- Con ✿ Know V , Know V_{ref} : Compute V_x
- ✿ Solve for T_x using V_x

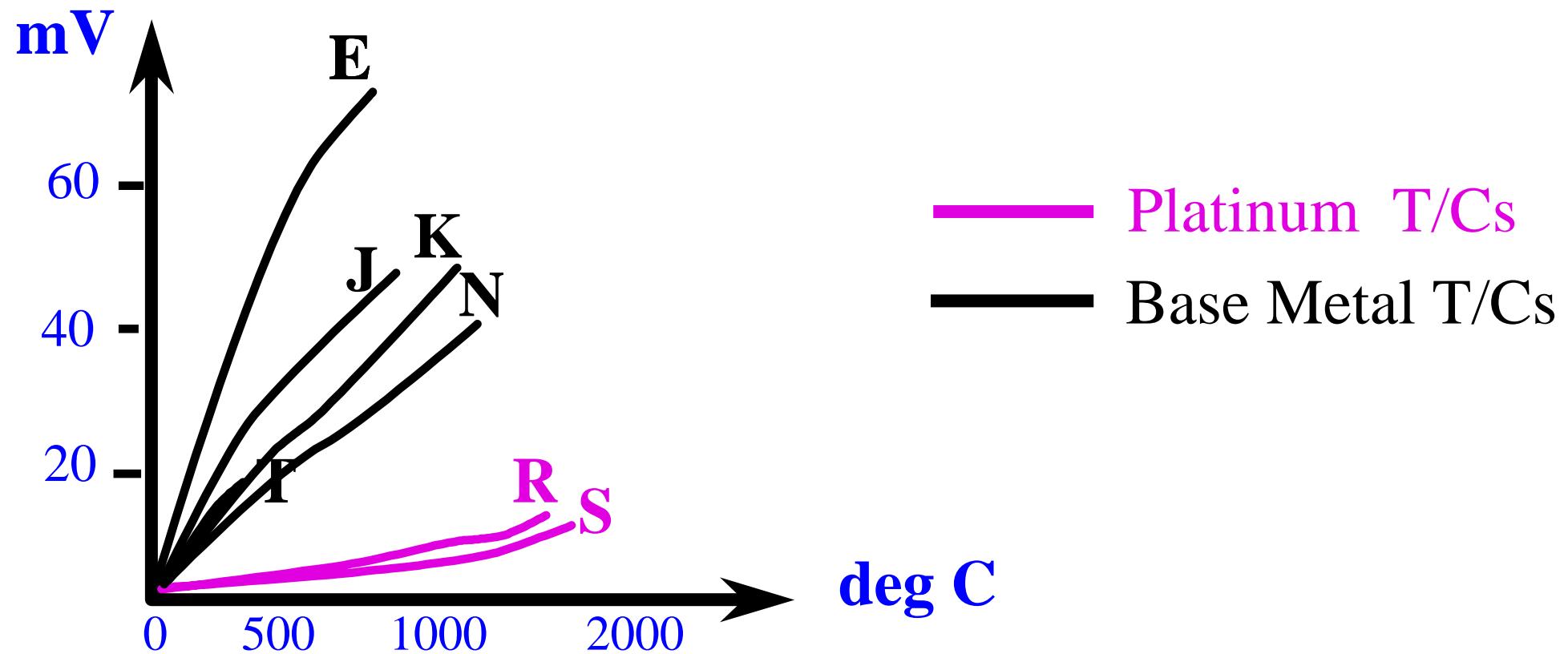


Linearization



- ✿ Polynomial: $T = a_0 + a_1 V + a_2 V^2 + a_3 V^3 + \dots + a_9 V^9$
- ✿ Nested (faster): $T = a_0 + V(a_1 + V(a_2 + V(a_3 + \dots + \dots)))$
- ✿ Small sectors (faster): $T = T_0 + bV + cV^2$
- ✿ Lookup table: Fastest, most memory

Common Thermocouples



✿ All have Seebeck coefficients in MICROvolts/deg.C

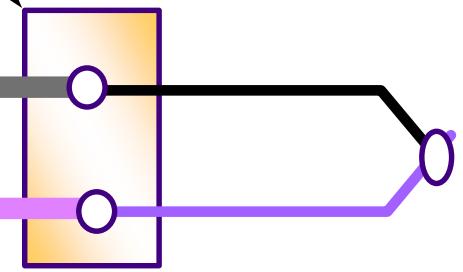
Common Thermocouples

| Type | Metals | Seebeck Coeff: $\mu\text{V/C}$ | |
|------|----------------|--------------------------------|-------------------------------------------|
| J | Fe-Con | 50 | ✿ Microvolt output is a tough measurement |
| K | Ni-Cr | 40 | |
| T | Cu-Con | 38 | ✿ Type "N" is fairly new.. |
| S | Pt/Rh-Pt | 10 | more rugged and higher |
| E | Ni/Cr-Con | 59 | temp. than type K, but |
| N | Ni/Cr/Si-Ni/Si | 39 | still cheap |

Extension Wires



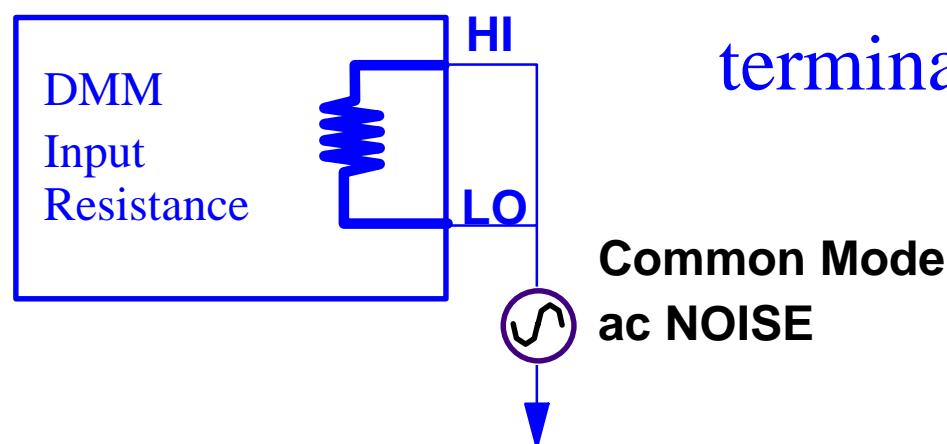
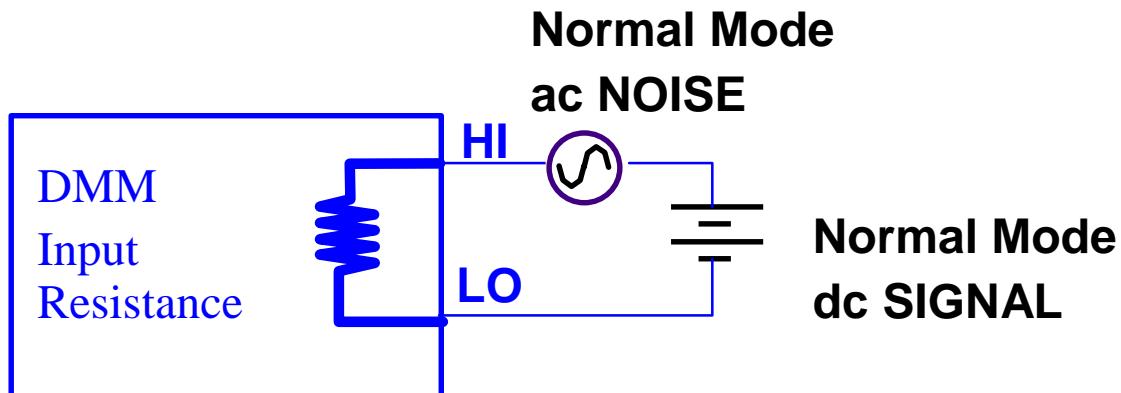
✿ Possible problem
here



Small diameter
measurement
wires

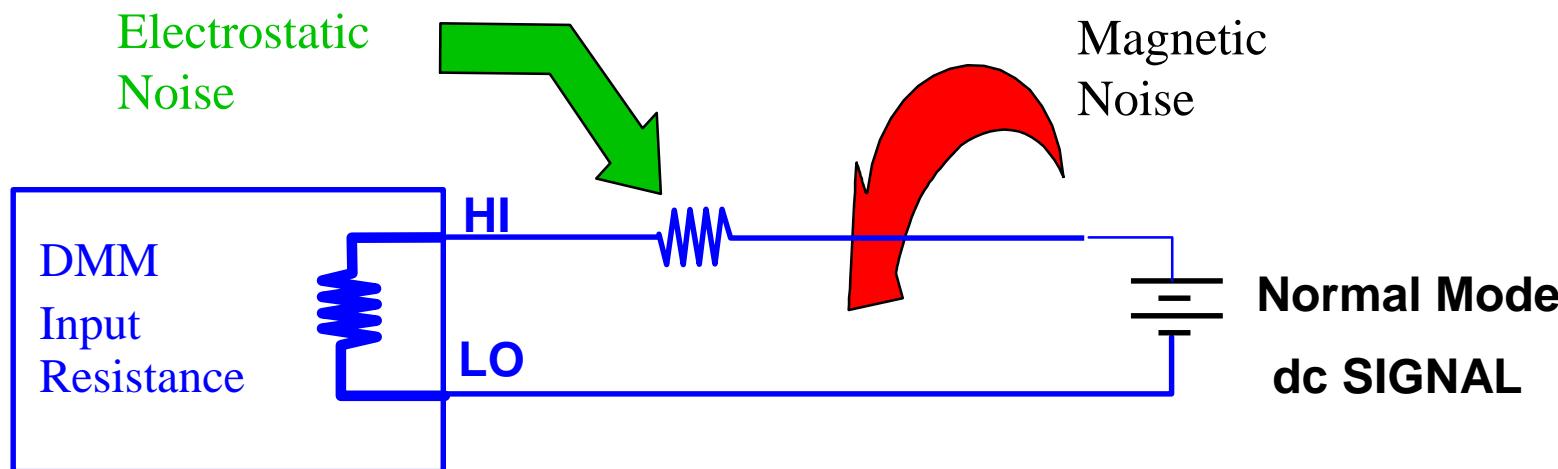
- ✿ Extension wires are cheaper, more rugged, but not exactly the same characteristic curve as the T/C.
- ✿ Keep extension/TC junction near room temperature
- ✿ Where is most of the signal generated in this circuit?

Noise: DMM Glossary

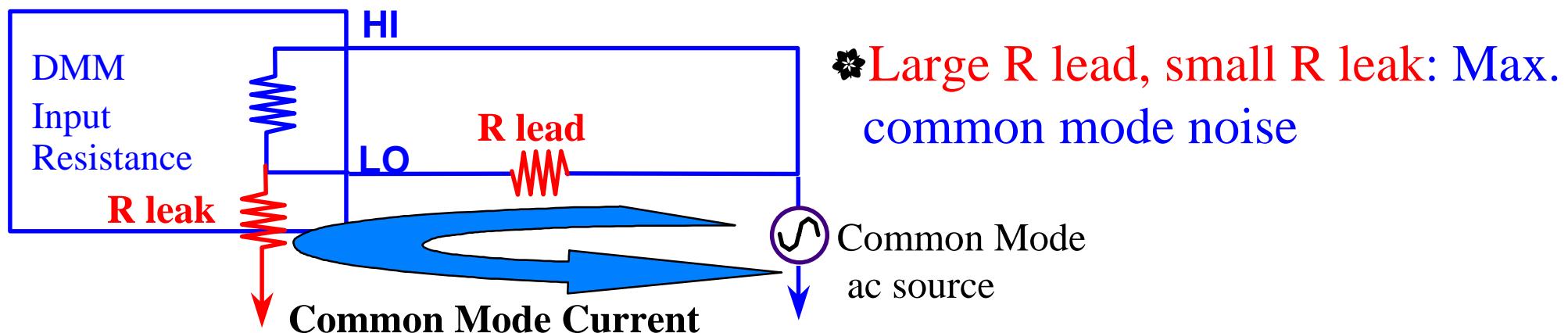


- ✿ **Normal Mode:** In series with input
- ✿ **Common Mode:** Both HI and LO terminals driven equally

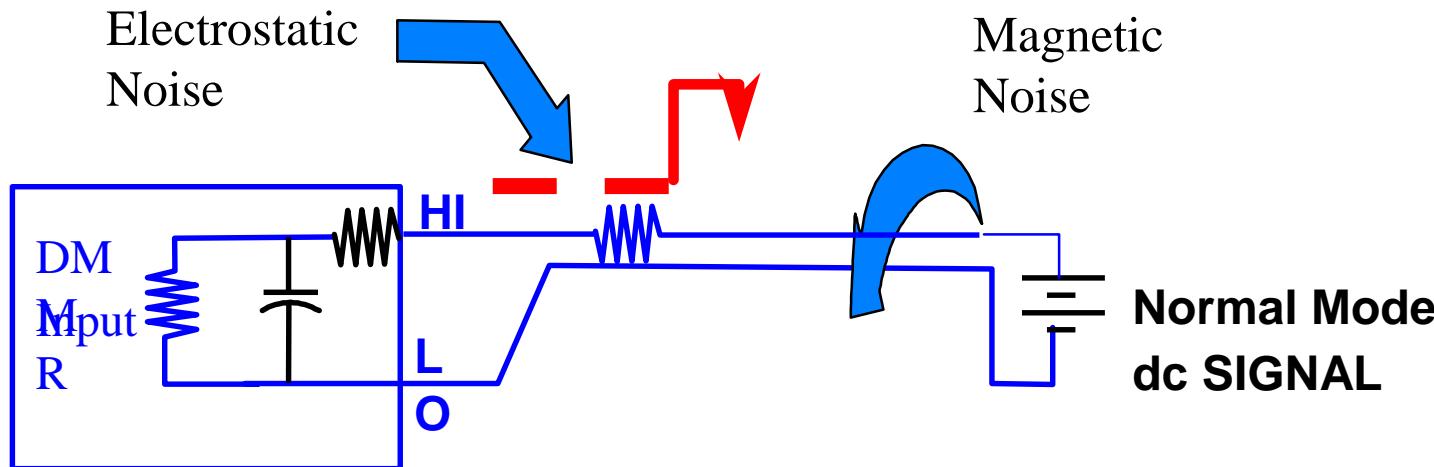
Generating noise



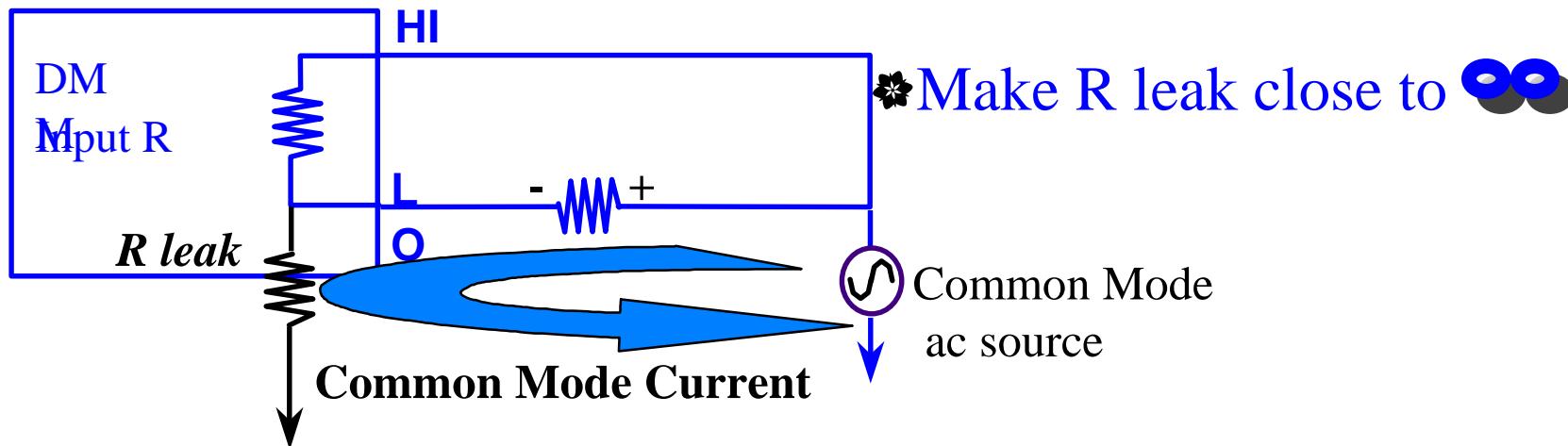
- ✿ Large surface area, high Rlead: Max. static coupling
- ✿ Large loop area: Max. magnetic coupling



Eliminating noise

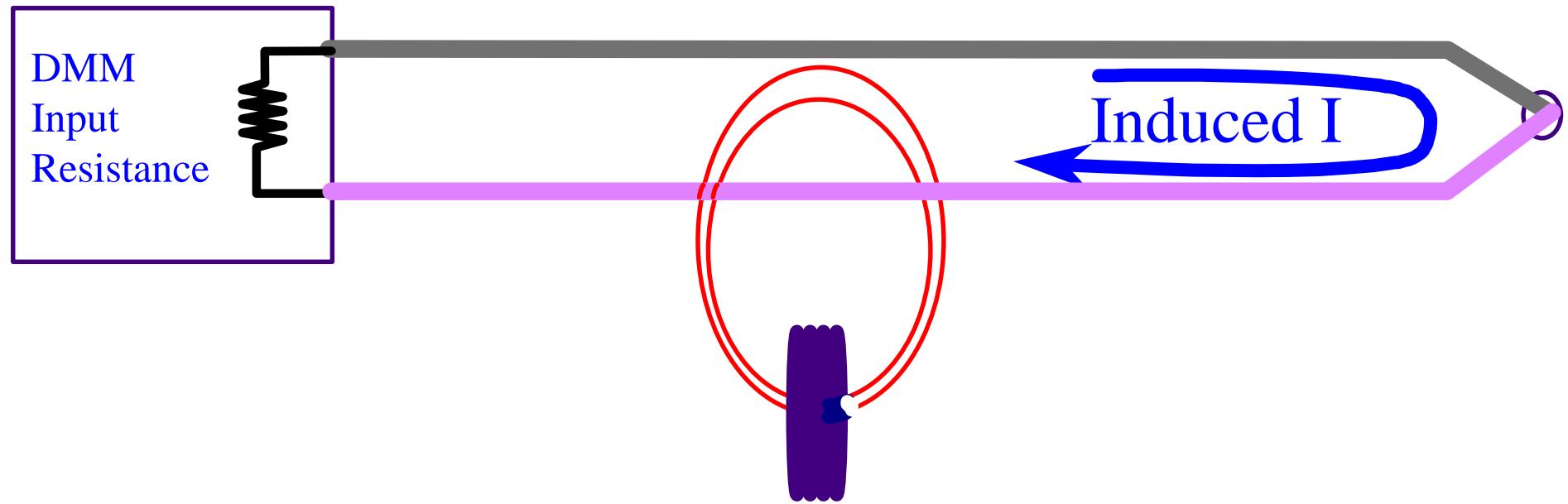


✿ Filter, shielding, small loop area
 (Caution: filter slows down the measurement)



Magnetic Noise

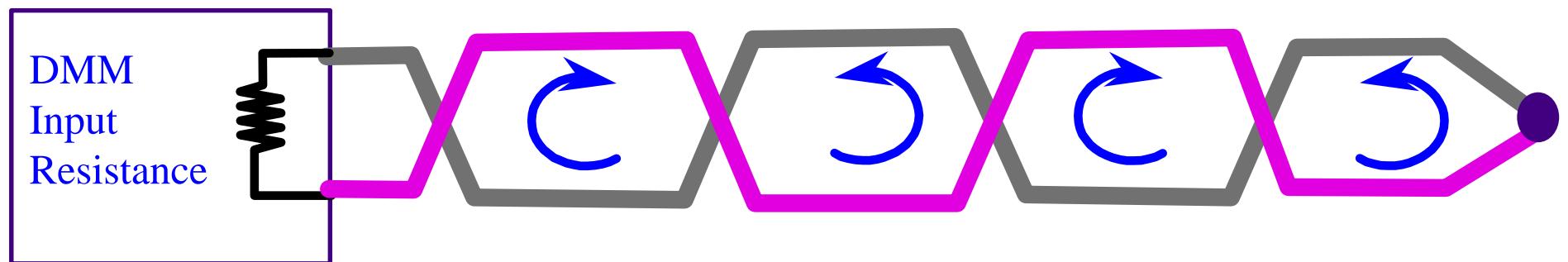
✿ Magnetic coupling



- ✿ Minimize area
- ✿ Twist leads
- ✿ Move away from strong fields

Reducing Magnetic Noise

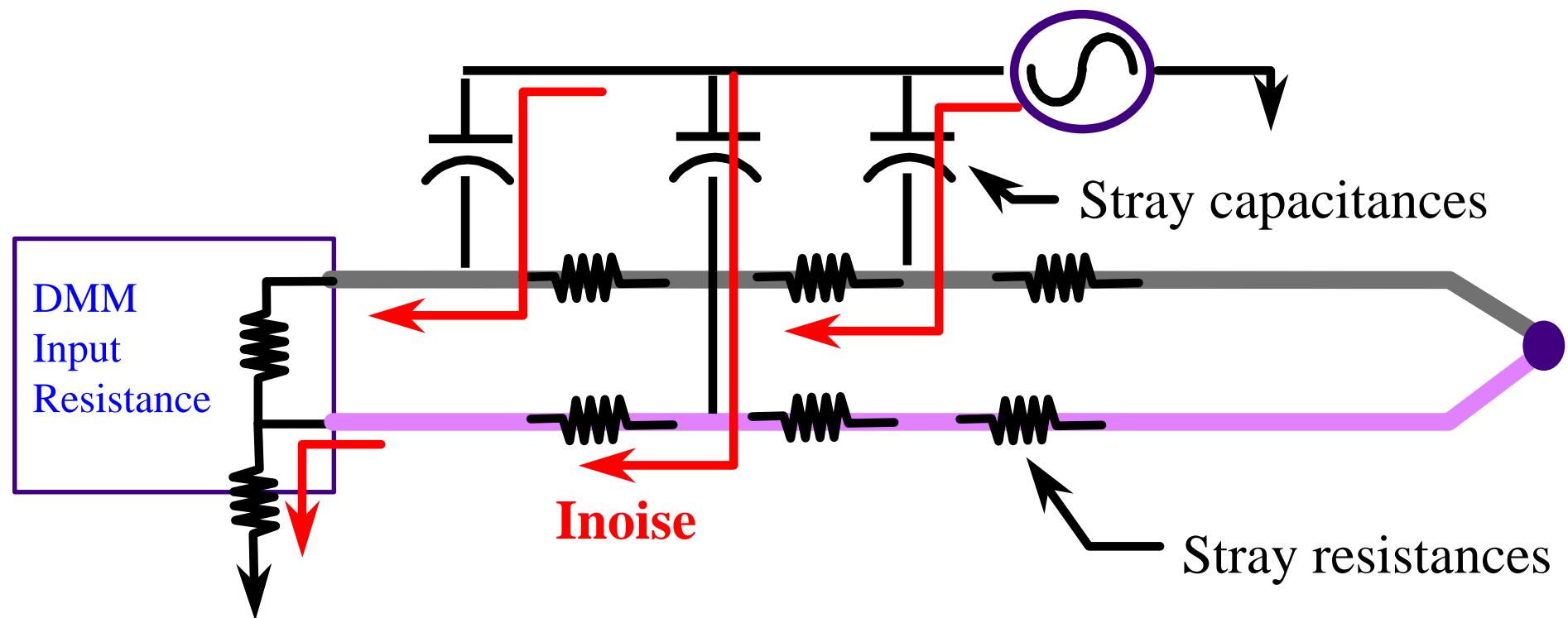
- ✿ Equal and opposite induced currents



- ✿ Even with twisted pair:
 - ✿ Minimize area
 - ✿ Move away from strong fields

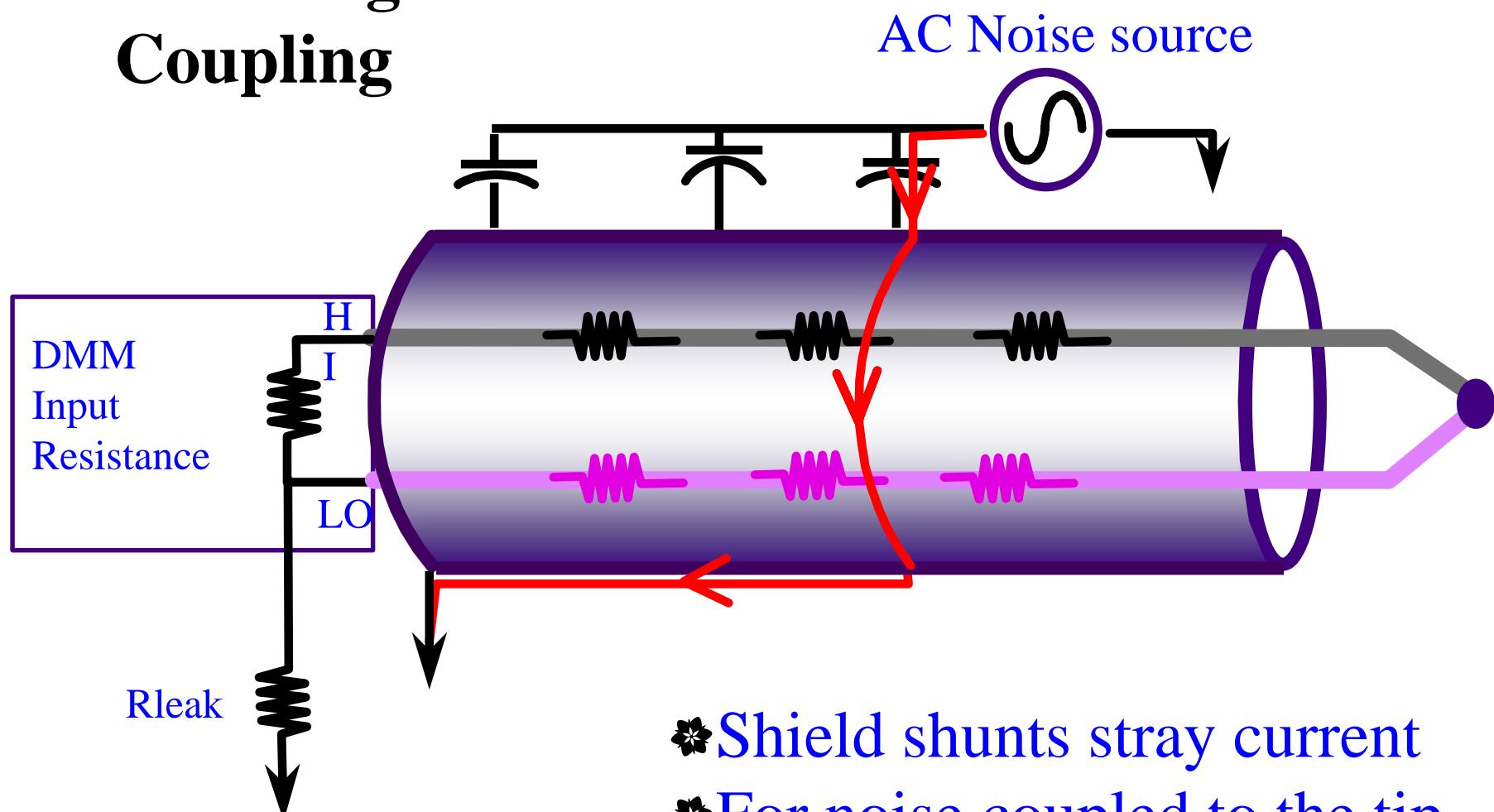
Electrostatic noise

AC Noise
source



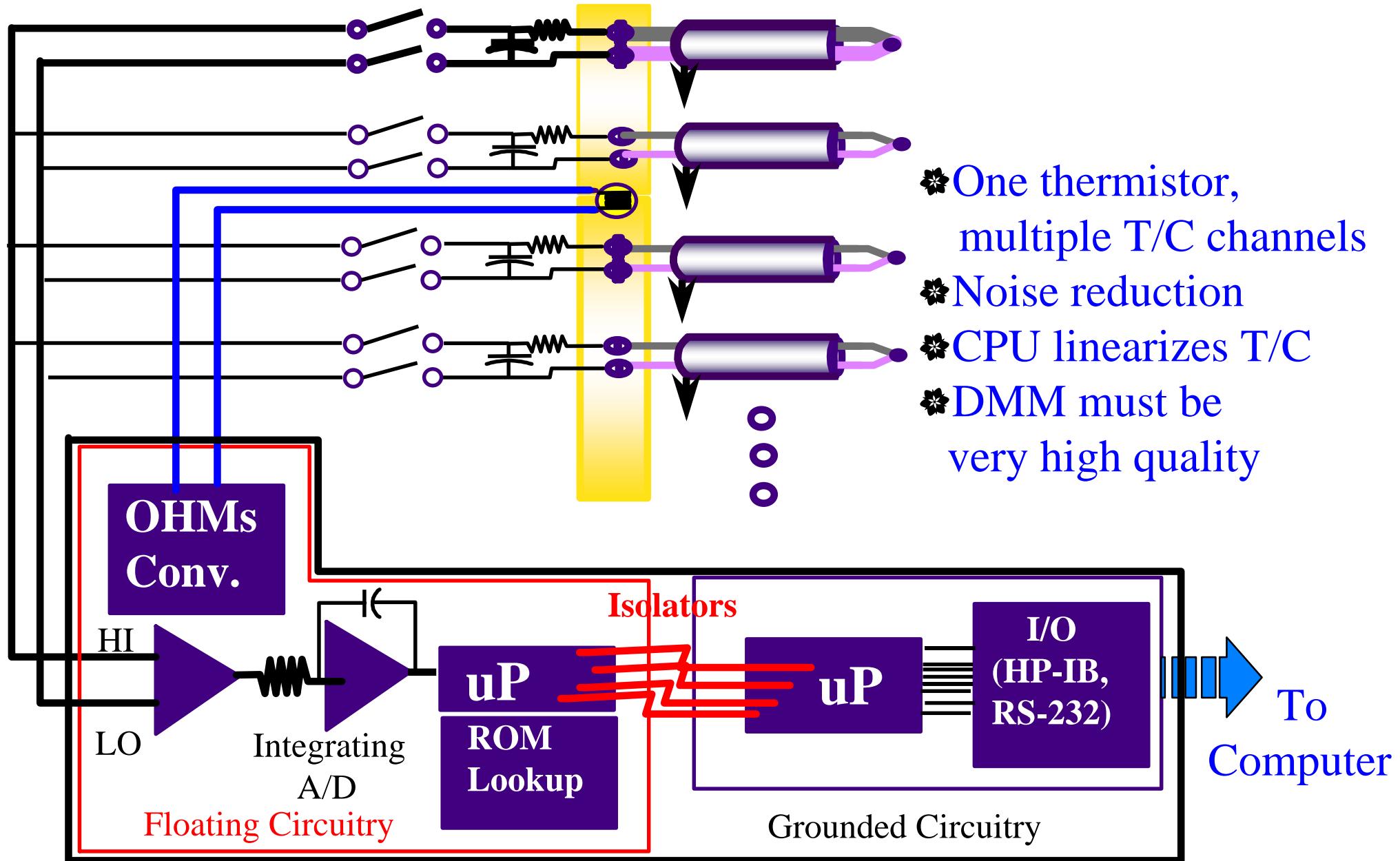
- ✿ Stray capacitance causes I noise
- ✿ DMM resistance to ground is important

Reducing Electrostatic Coupling

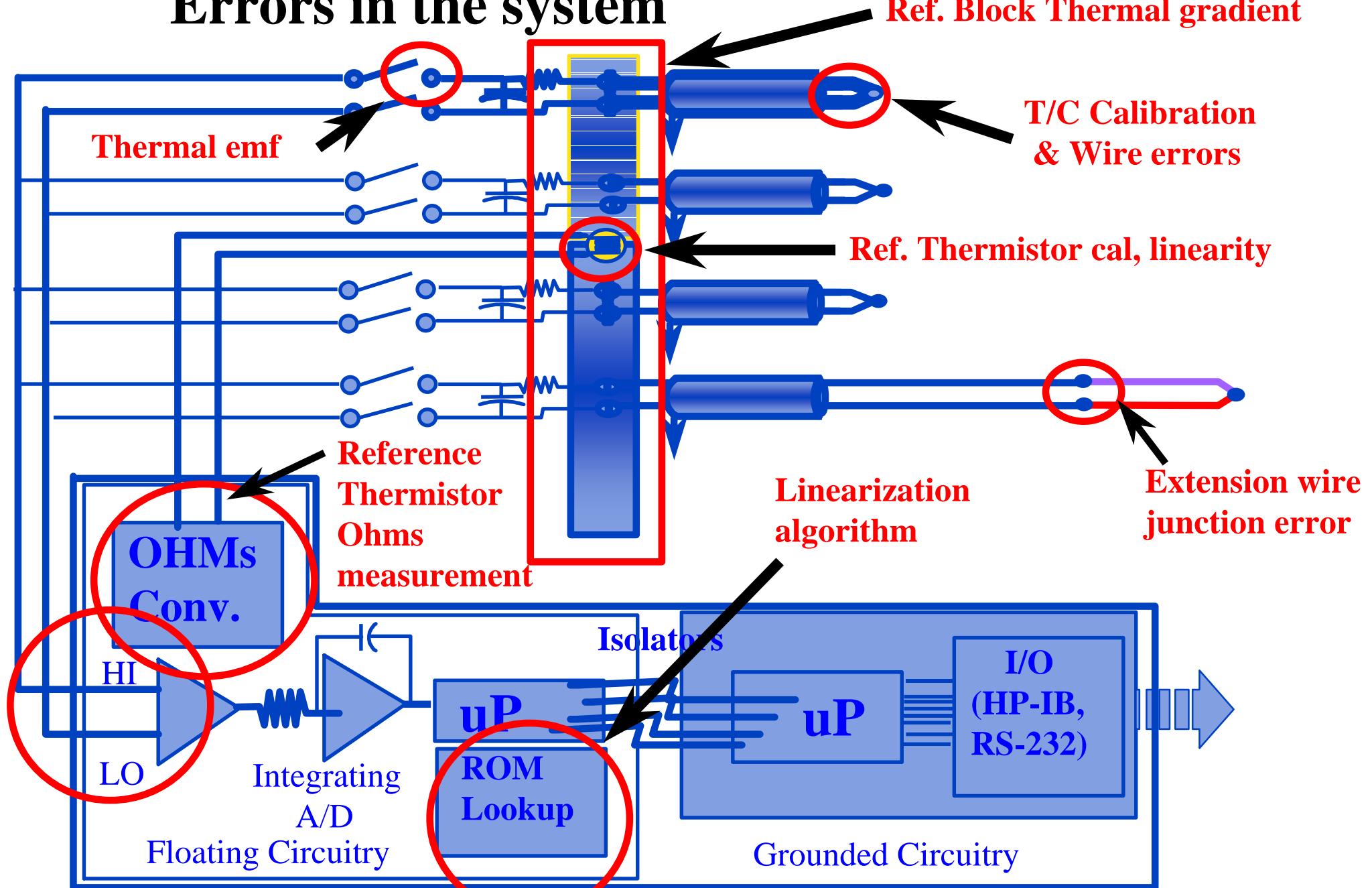


- ✿ Shield shunts stray current
- ✿ For noise coupled to the tip, Rleak is still important

A scanning system for T/Cs



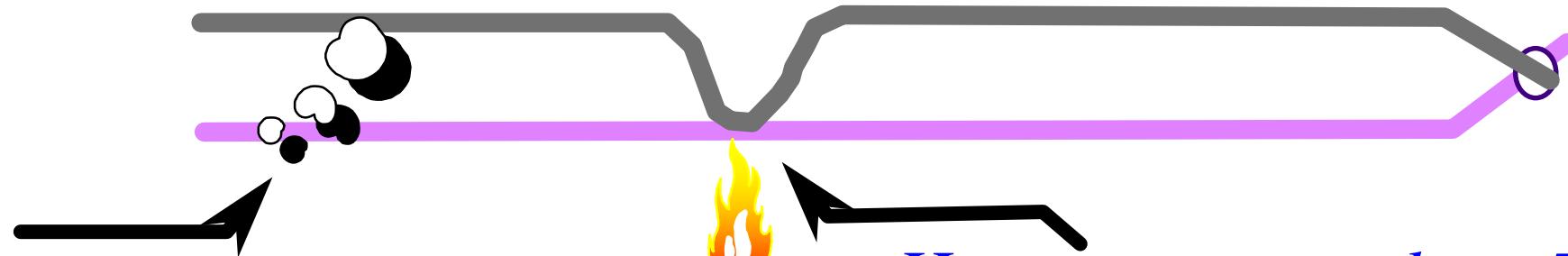
Errors in the system



Physical errors

- ✿ Shorts, shunt impedance
- ✿ Galvanic action
- ✿ Decalibration
- ✿ Sensor accuracy
- ✿ Thermal contact
- ✿ Thermal shunting

Physical Errors

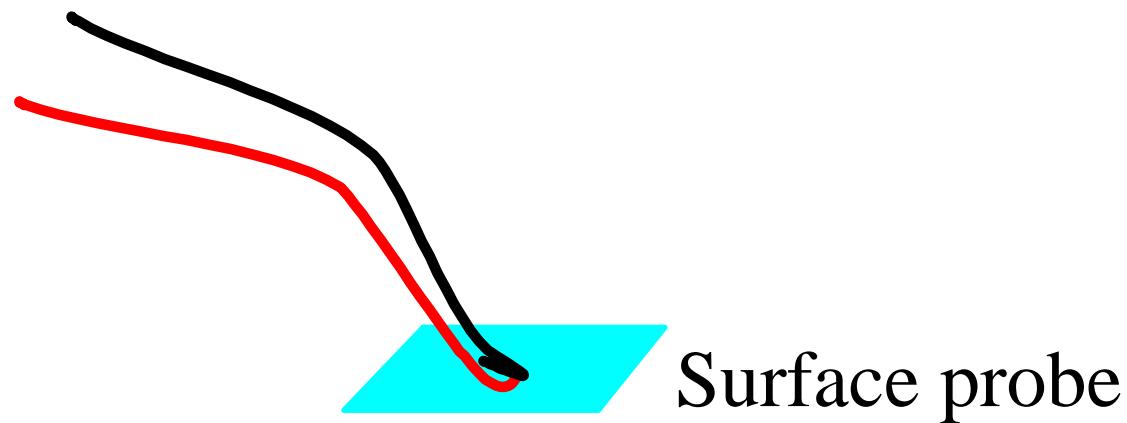


✿ Water droplets cause *galvanic action*; huge offsets

✿ Hot spot causes *shunt Z*, meter shows the **WRONG** temperature

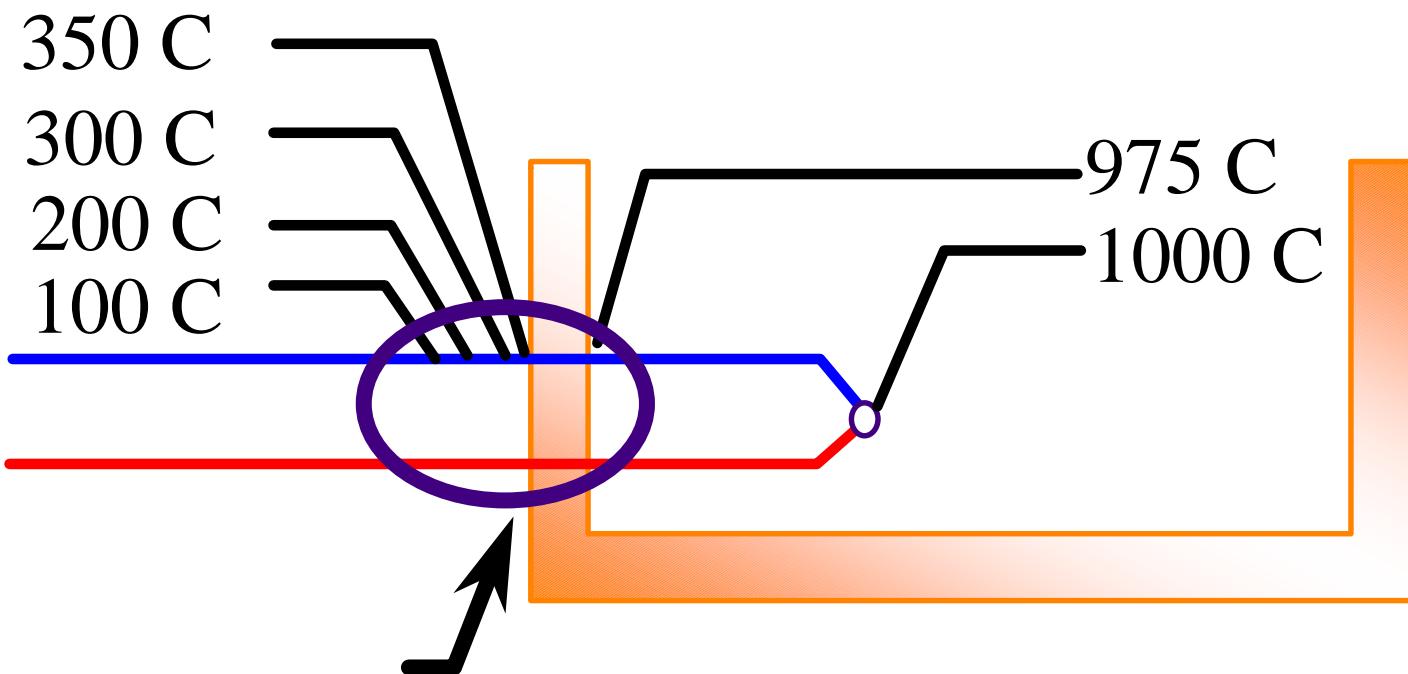
✿ Exceeding the T/C's range can cause permanent offset
✿ Real T/C's have absolute accuracy of 1 deg C @ 25C:
Calibrate often and take care

Physical error: Thermal contact



- ✿ Make sure thermal mass is much smaller than that of object being measured

Physical errors: Decalibration



This section
produces the
ENTIRE signal

- ✿ Don't exceed Tmax of T/C
- ✿ Temp. cycling causes work-hardening, decalibration
- ✿ Replace the GRADIENT section

Agenda

- ✿ Background, history
- ✿ Mechanical sensors
- ✿ Electrical sensors
 - ✿ Optical Pyrometer
 - ✿ RTD
 - ✿ Thermistor, IC
 - ✿ Thermocouple
- ✿ Summary & Examples

The basic 4 temperature sensors



RTD

- ✿ Most accurate
- ✿ Most stable
- ✿ Fairly linear
- ✿ Expensive
- ✿ Slow
- ✿ Needs I source
- ✿ Self-heating
- ✿ 4-wire meas.



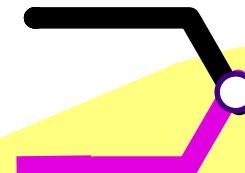
Thermistor

- ✿ High output
- ✿ Fast
- ✿ 2-wire meas.
- ✿ Very nonlinear
- ✿ Limited range
- ✿ Needs I source
- ✿ Self-heating
- ✿ Fragile



I.C.

- ✿ High output
- ✿ Most linear
- ✿ Cheap
- ✿ Limited variety
- ✿ Limited range
- ✿ Needs V source
- ✿ Self-heating



Thermocouple

- ✿ Wide variety
- ✿ Cheap
- ✿ Wide T. range
- ✿ No self-heating
- ✿ Hard to measure
- ✿ Relative T. only
- ✿ Nonlinear
- ✿ Special connectors

Absolute temperature sensors

Summary

- ✿ Innovation by itself is not enough...
you must develop standards
- ✿ Temperature is a very difficult,
mostly empirical measurement
- ✿ Careful attention to detail is required

Examples

Measurement

- ✿ Photochemical process control:
- ✿ Flower petal:
- ✿ Molten glass:
- ✿ Induction furnace:
- ✿ 100 degree Heat aging oven:

Sensor

- ✿ RTD (most accurate)
- ✿ Thermistor
(lowest thermal mass)
- ✿ Optical pyrometer
(hi temp, no contact)
- ✿ RTD (if <800C); or T/C
(Beware magnetic I noise)
- ✿ Any of the 4 sensors